# Asymptotic behavior of compositions of under-relaxed nonexpansive operators

J.-B. Baillon,<sup>1</sup> P. L. Combettes,<sup>2</sup> and R. Cominetti<sup>3</sup>

<sup>1</sup>Université Paris 1 Panthéon-Sorbonne SAMM – EA 4543 75013 Paris, France (Jean-Bernard.Baillon@univ-paris1.fr)

> <sup>2</sup>Sorbonne Universités – UPMC Univ. Paris 06 UMR 7598, Laboratoire Jacques-Louis Lions 75005, Paris, France (plc@math.jussieu.fr)

<sup>3</sup>Universidad de Chile Departamento de Ingeniería Industrial Santiago, Chile (rccc@dii.uchile.cl)

#### Abstract

In general there exists no relationship between the fixed point sets of the composition and of the average of a family of nonexpansive operators in Hilbert spaces. In this paper, we establish an asymptotic principle connecting the cycles generated by under-relaxed compositions of nonexpansive operators to the fixed points of the average of these operators. In the special case when the operators are projectors onto closed convex sets, we prove a conjecture by De Pierro which has so far been established only for projections onto affine subspaces.

**Keywords.** Cyclic projections, De Pierro's conjecture, fixed point, nonexpansive operator, projection operator, under-relaxed cycles.

2010 Mathematics Subject Classification. 47H09, 47H10, 47N10, 65K15

## 1 Introduction

Fixed points of compositions and averages of nonexpansive operators arise naturally in diverse settings; see for instance [4, 5, 10, 11] and the references therein. In general there is no simple relationship between the fixed point sets of such operators. In this paper we investigate the connection of the fixed points of the average operator with the limits of a family of underrelaxed compositions. More precisely, we consider the framework described in the following standing assumption.

**Assumption 1.1**  $\mathcal{H}$  is a real Hilbert space, D is a nonempty, closed, convex subset of  $\mathcal{H}$ ,  $m \ge 2$  is an integer,  $I = \{1, \ldots, m\}$ ,  $(T_i)_{i \in I}$  is a family of nonexpansive operators from D to D, and  $(\operatorname{Fix} T_i)_{i \in I}$  is the family of associated fixed point sets. Moreover, we set

$$\begin{cases} T = \frac{1}{m} \sum_{i \in I} T_i \\ R = T_m \circ \cdots \circ T_1 \\ (\forall \varepsilon \in ]0, 1[) \ R^{\varepsilon} = (\operatorname{Id} + \varepsilon (T_m - \operatorname{Id})) \circ \cdots \circ (\operatorname{Id} + \varepsilon (T_1 - \operatorname{Id})). \end{cases}$$
(1.1)

When the operators  $(T_i)_{i \in I}$  have common fixed points, Fix  $T = \bigcap_{i=1}^{m} \text{Fix } T_i \neq \emptyset$  [5, Proposition 4.32]. If, in addition, they are strictly nonexpansive in the sense that

$$(\forall i \in I)(\forall x \in D \setminus \operatorname{Fix} T_i)(\forall y \in \operatorname{Fix} T_i) \quad ||T_i x - y|| < ||x - y||,$$
(1.2)

it also holds that Fix  $R = \bigcap_{i \in I} \text{Fix } T_i$  [5, Corollary 4.36], and therefore Fix R = Fix T. However, in the general case when  $\bigcap_{i \in I} \text{Fix } T_i = \emptyset$ , the question has been long standing and remains open even for convex projection operators, e.g., [10, Section 8.3.2] and [14]. Even when m = 2 and  $T_1$ and  $T_2$  are resolvents of maximally monotone operators, there does not seem to exist a simple relationship between Fix R and Fix T [18], except for convex projection operators, in which case Fix T = (1/2)(Fix R + Fix R'), with  $R' = T_1 \circ T_2$  (see [3, 13] for related results, and [7] for the case of  $m \ge 3$  resolvents).

When  $(T_i)_{i \in I} = (P_i)_{i \in I}$  are projection operators onto nonempty closed convex sets  $(C_i)_{i \in I}$ , Fix T is the set of minimizers of the average square-distance function [3, 13, 15]

$$\Phi \colon \mathcal{H} \to \mathbb{R} \colon x \mapsto \frac{1}{2m} \sum_{i \in I} d_{C_i}^2(x), \tag{1.3}$$

while Fix R is related to the set of Nash equilibria of a cyclic projection game. Indeed, the fixed point equation x = Rx can be restated as a system of equations in  $(x_1, \ldots, x_m) \in \mathcal{H}^m$ , namely

$$\begin{cases} x_1 &= P_1 x_m \\ x_2 &= P_2 x_1 \\ &\vdots \\ x_m &= P_m x_{m-1}, \end{cases}$$
(1.4)

which characterize the Nash equilibria of a game in which each player  $i \in I$  selects a strategy  $x_i \in C_i$  to minimize the payoff  $x \mapsto ||x - x_{i-1}||$ , with the convention  $x_0 = x_m$ . It is worth

noting that, for  $m \ge 3$ , these Nash equilibria cannot be characterized as minimizers of any function  $\Psi: \mathcal{H}^m \to \mathbb{R}$  over  $C_1 \times \cdots \times C_m$  [2], which further reinforces the lack of hope for simple connections between Fix R and Fix T. It was shown in [16] that, if one of the sets is bounded, for every  $y_0 \in \mathcal{H}$ , the sequence  $(y_{km+1}, \ldots, y_{km+m})_{k \in \mathbb{N}}$  generated by the periodic best-response dynamics

$$(\forall k \in \mathbb{N}) \qquad \begin{cases} y_{km+1} &= P_1 y_{km} \\ y_{km+2} &= P_2 y_{km+1} \\ &\vdots \\ y_{km+m} &= P_m y_{km+m-1}, \end{cases}$$
(1.5)

converges weakly to a solution  $(x_1, \ldots, x_m)$  to (1.4) (see Fig. 1). Working in a similar direction,

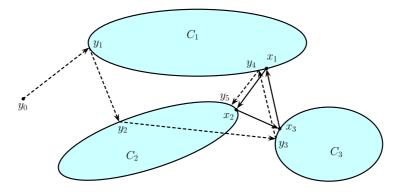


Figure 1: Cycles in the method of periodic projections.

and motivated by the work of [12] on under-relaxed projection methods for solving inconsistent systems of affine inequalities, De Pierro considered in [14] an under-relaxed version of (1.5), namely

$$(\forall k \in \mathbb{N}) \qquad \begin{cases} y_{km+1}^{\varepsilon} &= (\mathrm{Id} + \varepsilon (P_1 - \mathrm{Id})) y_{km}^{\varepsilon} \\ y_{km+2}^{\varepsilon} &= (\mathrm{Id} + \varepsilon (P_2 - \mathrm{Id})) y_{km+1}^{\varepsilon} \\ \vdots \\ y_{km+m}^{\varepsilon} &= (\mathrm{Id} + \varepsilon (P_m - \mathrm{Id})) y_{km+m-1}^{\varepsilon}. \end{cases}$$
(1.6)

Under mild conditions the resulting sequence  $(y_{km+1}^{\varepsilon}, y_{km+2}^{\varepsilon}, \dots, y_{km+m}^{\varepsilon})_{k \in \mathbb{N}}$  converges weakly to a limit cycle that satisfies the coupled equations

$$(\forall \varepsilon \in ]0,1[) \quad \begin{cases} x_1^{\varepsilon} = (\operatorname{Id} + \varepsilon (P_1 - \operatorname{Id})) x_m^{\varepsilon} \\ x_2^{\varepsilon} = (\operatorname{Id} + \varepsilon (P_2 - \operatorname{Id})) x_1^{\varepsilon} \\ \vdots \\ x_m^{\varepsilon} = (\operatorname{Id} + \varepsilon (P_m - \operatorname{Id})) x_{m-1}^{\varepsilon}. \end{cases}$$
(1.7)

In [14, Conjecture I], De Pierro conjectured that as  $\varepsilon \to 0$  these limit cycles  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,1[}$ shrink towards a single point which is a minimizer of  $\Phi$ , i.e., a fixed point of T. In contrast with (1.4), the solutions of which do not satisfy any optimality criteria, this conjecture suggests an asymptotic variational principle for the cycles obtained as limits of the under-relaxed version of (1.5). An important contribution was made in [6], where it was shown that De Pierro's conjecture is true for families of closed affine subspaces which satisfy a certain regularity condition.

In this paper we investigate the asymptotic behavior of the under-relaxed cycles

$$\begin{cases} x_1^{\varepsilon} = (\operatorname{Id} + \varepsilon (T_1 - \operatorname{Id})) x_m^{\varepsilon} \\ x_2^{\varepsilon} = (\operatorname{Id} + \varepsilon (T_2 - \operatorname{Id})) x_1^{\varepsilon} \\ \vdots \\ x_m^{\varepsilon} = (\operatorname{Id} + \varepsilon (T_m - \operatorname{Id})) x_{m-1}^{\varepsilon} \end{cases}$$
(1.8)

as  $\varepsilon \to 0$  in the general setting of Assumption 1.1. In Section 2 we present a first general convergence result, which establishes conditions under which the limits as  $\varepsilon \to 0$  of the *m* curves  $(x_i^{\varepsilon})_{\varepsilon \in ]0,1[}$   $(i \in I)$  exist and all coincide with a fixed point of *T*. This result not only gives conditions under which De Pierro's conjecture is true, but also extends its scope from projection operators to arbitrary nonexpansive operators. In Section 3 we revisit the problem from a constructive angle. Given an initial point  $y_0 \in D$  and  $\varepsilon \in ]0,1[$ , it is known [5, Theorem 5.22] that the cycles in (1.8) can be constructed iteratively as the weak limit of the periodic process

$$(\forall k \in \mathbb{N}) \qquad \begin{cases} y_{km+1}^{\varepsilon} &= (\operatorname{Id} + \varepsilon (T_1 - \operatorname{Id})) y_{km}^{\varepsilon} \\ y_{km+2}^{\varepsilon} &= (\operatorname{Id} + \varepsilon (T_2 - \operatorname{Id})) y_{km+1}^{\varepsilon} \\ &\vdots \\ y_{km+m}^{\varepsilon} &= (\operatorname{Id} + \varepsilon (T_m - \operatorname{Id})) y_{km+m-1}^{\varepsilon}. \end{cases}$$
(1.9)

We analyze the connection between this iterative process and the trajectories of the evolution equation

$$\begin{cases} \mathsf{u}'(t) + \mathsf{u}(t) = T\mathsf{u}(t) \text{ on } ]0, +\infty[\\ \mathsf{u}(0) = y_0, \end{cases}$$
(1.10)

and then prove extended versions of De Pierro's conjecture under various assumptions.

**Notation.** The scalar product of  $\mathcal{H}$  is denoted by  $\langle \cdot | \cdot \rangle$  and the associated norm by  $\| \cdot \|$ . The symbols  $\rightarrow$  and  $\rightarrow$  denote, respectively, weak and strong convergence, and Id denotes the identity operator. The closed ball of center  $x \in \mathcal{H}$  and radius  $\rho \in ]0, +\infty[$  is denoted by  $B(x; \rho)$ . Given a nonempty closed convex subset  $C \subset \mathcal{H}$ , the distance function to C and the projection operator onto C are respectively denoted by  $d_C$  and  $P_C$ .

## 2 Convergence of general families of under-relaxed cycles

We investigate the asymptotic behavior of the cycles  $(x_i^{\varepsilon})_{i \in I}$  defined by (1.8) when  $\varepsilon \to 0$ . Let us remark that such a cycle  $(x_i^{\varepsilon})_{i \in I}$  is in bijection with the fixed points of the composition  $R^{\varepsilon}$ of (1.1). Indeed,  $z^{\varepsilon} = x_m^{\varepsilon}$  is a fixed point of  $R^{\varepsilon}$ ; conversely, each  $z^{\varepsilon} \in \text{Fix } R^{\varepsilon}$  generates a cycle by setting, for every  $i \in I$ ,  $x_i^{\varepsilon} = (\text{Id} + \varepsilon(T_i - \text{Id}))x_{i-1}^{\varepsilon}$ , where  $x_0^{\varepsilon} = z^{\varepsilon}$ . This motivates our second standing assumption. Assumption 2.1 For every  $\varepsilon \in [0,1[, R^{\varepsilon} \text{ is given by } (1.1) \text{ and }$ 

$$(\exists \eta \in ]0,1])(\exists \beta \in ]0,+\infty[)(\forall \varepsilon \in ]0,\eta[)(\exists z^{\varepsilon} \in \operatorname{Fix} R^{\varepsilon}) \quad ||z^{\varepsilon}|| \leq \beta.$$

$$(2.1)$$

For later reference, we record the fact that under this assumption the cycles in (1.8) can be obtained as weak limits of the iterative process (1.9).

**Proposition 2.2** Suppose that Assumptions 1.1 and 2.1 are satisfied. Let  $y_0 \in D$  and  $\varepsilon \in [0, \eta[$ . Then the sequence  $(y_{km+1}^{\varepsilon}, \ldots, y_{km+m}^{\varepsilon})_{k \in \mathbb{N}}$  produced by (1.9) converges weakly to an m-tuple  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})$  which satisfies (1.8).

*Proof.* This follows from [5, Theorem 5.22].

The following result provides sufficient conditions for Assumption 2.1 to hold.

**Proposition 2.3** Suppose that Assumption 1.1 holds, together with one of the following.

- (i) For some  $j \in I$ ,  $T_j$  has bounded range.
- (ii) D is bounded.

Then Assumption 2.1 is satisfied.

*Proof.* It is clear that (ii) is a special case of (i). Suppose that (i) holds. Fix  $\varepsilon \in [0, 1]$  and  $y \in D$ , and take  $\rho \in [\max_{i \in I \setminus \{j\}} ||T_i y - y||, +\infty[$  such that  $T_j(D) \subset B(y; \rho)$ . Furthermore, let  $x \in D$ , set  $x_0 = x$ , and define recursively  $x_i = (1 - \varepsilon)x_{i-1} + \varepsilon T_i x_{i-1}$ , so that  $x_m = R^{\varepsilon} x$ . Then

$$(\forall i \in I \setminus \{j\}) \quad \|x_i - y\| = \|(1 - \varepsilon)(x_{i-1} - y) + \varepsilon(T_i x_{i-1} - y)\|$$
  
$$\leq (1 - \varepsilon)\|x_{i-1} - y\| + \varepsilon\|T_i x_{i-1} - T_i y\| + \varepsilon\|T_i y - y\|$$
  
$$\leq \|x_{i-1} - y\| + \varepsilon\rho$$
(2.2)

and

$$||x_j - y|| \leq (1 - \varepsilon) ||x_{j-1} - y|| + \varepsilon ||T_j x_{j-1} - y||$$
  
$$\leq (1 - \varepsilon) ||x_{j-1} - y|| + \varepsilon \rho.$$
(2.3)

By applying inductively (2.2) and (2.3) to majorize  $||x_m - y||$ , we obtain

$$||R^{\varepsilon}x - y|| = ||x_m - y|| \leq (1 - \varepsilon)||x - y|| + \varepsilon m\rho.$$
(2.4)

This implies that  $R^{\varepsilon}$  maps  $D \cap B(y; m\rho)$  to itself. Hence, the Browder–Göhde–Kirk theorem (see [5, Theorem 4.19]) asserts that  $R^{\varepsilon}$  has a fixed point in  $B(y; m\rho)$ . Moreover, if x is a fixed point of  $R^{\varepsilon}$ , (2.4) gives  $||x - y|| \leq m\rho$ , which shows that (2.1) holds with  $\eta = 1$  and  $\beta = ||y|| + m\rho$ .

To illustrate Assumption 2.1, it is instructive to consider the following examples.

**Example 2.4** The following variant of the example discussed in [14, Section 3] shows that (2.1) is a non trivial assumption:  $\mathcal{H}$  is the Euclidean plane, m = 3,  $\alpha \in \mathbb{R}$ ,  $\beta \in \mathbb{R}$ ,  $\gamma \in ]0, +\infty[$ ,  $\varepsilon \in ]0, 1[$ , and  $(T_i)_{1 \leq i \leq 3}$  are, respectively, the projection operators onto the sets

$$C_1 = \mathbb{R} \times \{\alpha\}, \quad C_2 = \mathbb{R} \times \{\beta\}, \quad \text{and} \quad C_3 = \{(\xi_1, \xi_2) \in [0, +\infty[^2 \mid \xi_1 \xi_2 \ge \gamma]\}.$$
(2.5)

Then we have

$$\begin{cases} \operatorname{Fix} T = \left\{ (\xi_1, \xi_2) \in C_3 \mid \xi_2 = (\alpha + \beta)/2 \right\} \\ \operatorname{Fix} R = \left\{ (\xi_1, \xi_2) \in C_3 \mid \xi_2 = \beta \right\} \\ \operatorname{Fix} R^{\varepsilon} = \left\{ (\xi_1, \xi_2) \in C_3 \mid \xi_2 = \left( (1 - \varepsilon)\alpha + \beta \right)/(2 - \varepsilon) \right\}. \end{cases}$$
(2.6)

Thus, depending on the values of  $\alpha$  and  $\beta$ , we can have Fix  $T = \text{Fix } R \neq \emptyset$ , Fix  $T = \text{Fix } R = \emptyset$ , Fix  $T \neq \text{Fix } R = \emptyset$ , Fix  $R \neq \text{Fix } T = \emptyset$ , or  $\emptyset \neq \text{Fix } R \neq \text{Fix } T \neq \emptyset$ . Now set  $\eta = 1 + \beta/\alpha$ . We consider two situations.

- (i) Suppose that  $\alpha + \beta < 0 < \beta$ . Then  $\eta \in ]0,1[$ , and Fix  $R^{\varepsilon} = \emptyset$  if  $\varepsilon \leq \eta$ , while Fix  $R^{\varepsilon} \neq \emptyset$  if  $\varepsilon > \eta$ .
- (ii) Suppose that  $\beta < 0 < \alpha + \beta$ . Then  $\eta \in ]0,1[$ , and Fix  $R^{\varepsilon} \neq \emptyset$  if  $\varepsilon < \eta$ , while Fix  $R^{\varepsilon} = \emptyset$  if  $\varepsilon \ge \eta$ . Moreover, setting

$$(\forall \varepsilon \in ]0, \eta[) \quad \begin{cases} y^{\varepsilon} = \left(\frac{2\gamma}{(1-\varepsilon)\alpha+\beta} + \frac{1}{\varepsilon}, \frac{(1-\varepsilon)\alpha+\beta}{2-\varepsilon}\right) \in \operatorname{Fix} R^{\varepsilon} \\ z^{\varepsilon} = \left(\frac{(2-\varepsilon)\gamma}{(1-\varepsilon)\alpha+\beta}, \frac{(1-\varepsilon)\alpha+\beta}{2-\varepsilon}\right) \in \operatorname{Fix} R^{\varepsilon}. \end{cases}$$
(2.7)

we see that  $(y^{\varepsilon})_{\varepsilon\in]0,\eta[}$  is unbounded, while  $(z^{\varepsilon})_{\varepsilon\in]0,\eta[}$  is bounded. It is worth noting that when  $\alpha = -1$  and  $\beta = \gamma = 1$  we have Fix  $T = \emptyset$  and Fix  $R^{\varepsilon} = [(2-\varepsilon)/\varepsilon, +\infty[\times\{\varepsilon/(2-\varepsilon)\},$ which is nonempty but diverges as  $\varepsilon \to 0$ . In this setting, (2.1) fails because  $(\forall z^{\varepsilon} \in \operatorname{Fix} R^{\varepsilon})$  $\|z^{\varepsilon}\| \ge (2-\varepsilon)/\varepsilon \to +\infty$  as  $\varepsilon \to 0$ .

**Example 2.5** In Example 2.4 the sets  $(\operatorname{Fix} T_i)_{1 \leq i \leq 3}$  are nonempty, and one may ask whether this plays a role in the nonemptiness of  $\operatorname{Fix} R$ ,  $\operatorname{Fix} T$ , or  $\operatorname{Fix} R^{\varepsilon}$ . To see that such is not the case, define  $T_3$  as in Example 2.4, and consider the modified operators  $T_1: (\xi_1, \xi_2) \mapsto (\xi_1 + \mu, \alpha)$  and  $T_2: (\xi_1, \xi_2) \mapsto (\xi_1 - \mu, \beta)$ , where  $\mu > 0$ . Although now the nonexpansive operators  $T_1$  and  $T_2$ have no fixed points, the operators T, R, and  $R^{\varepsilon}$  remain unchanged.

**Example 2.6** By considering products of sets of the form (2.5) one can build an example in which Fix T is nonempty but the sets  $(\text{Fix } R^{\varepsilon})_{\varepsilon \in ]0,1[}$  are empty. More precisely, let  $\mathcal{H} = \ell^2(\mathbb{N})$ , and let  $(\alpha_n)_{n \in \mathbb{N}}$ ,  $(\beta_n)_{n \in \mathbb{N}}$ , and  $(\gamma_n)_{n \in \mathbb{N}}$  be sequences in  $\ell^2(\mathbb{N})$  such that  $(\gamma_n/(\alpha_n + \beta_n))_{n \in \mathbb{N}} \in \ell^2(\mathbb{N})$  and  $(\forall n \in \mathbb{N})$   $\beta_n < 0 < \alpha_n + \beta_n$  and  $\gamma_n > 0$ . Set

$$\begin{cases} C_1 = \left\{ (\xi_n)_{n \in \mathbb{N}} \in \ell^2(\mathbb{N}) \mid (\forall n \in \mathbb{N}) \ \xi_{2n} = \alpha_n \right\} \\ C_2 = \left\{ (\xi_n)_{n \in \mathbb{N}} \in \ell^2(\mathbb{N}) \mid (\forall n \in \mathbb{N}) \ \xi_{2n} = \beta_n \right\} \\ C_3 = \left\{ (\xi_n)_{n \in \mathbb{N}} \in \ell^2(\mathbb{N}) \mid (\forall n \in \mathbb{N}) \ \xi_n > 0 \text{ and } \xi_{2n-1} \xi_{2n} \ge \gamma_n \right\}. \end{cases}$$
(2.8)

Then Fix  $T \neq \emptyset$  but, for  $\varepsilon \in [0, 1[$ , we have Fix  $R^{\varepsilon} \neq \emptyset$  if and only if  $(\forall n \in \mathbb{N}) \varepsilon < 1 + \beta_{2n+1}/\alpha_{2n+1}$ . In particular if we take, for every  $n \in \mathbb{N} \setminus \{0\}$ ,  $\alpha_n = (n+1)/n^2$ ,  $\beta_n = -1/n$ , and  $\gamma_n = 1/n^3$ , then Fix  $R^{\varepsilon} = \emptyset$  for every  $\varepsilon \in [0, 1[$ .

**Example 2.7** ([6, Example 4.1]) Let m = 2, and let  $T_1$  and  $T_2$  be the projection operators onto closed affine subspaces  $C_1 \subset \mathcal{H}$  and  $C_2 \subset \mathcal{H}$ , respectively. If  $\mathcal{H}$  is finite-dimensional, the sets Fix R, (Fix  $R^{\varepsilon})_{\varepsilon \in ]0,1[}$ , and Fix T are nonempty; if  $\mathcal{H}$  is infinite-dimensional, there exist  $C_1$  and  $C_2$  such that these sets are all empty. However, if the vector subspace  $(C_1 - C_1) + (C_2 - C_2)$  is closed, then Fix  $T \neq \emptyset$  and  $(\forall \varepsilon \in ]0,1[)$  Fix  $R^{\varepsilon} \neq \emptyset$ .

The next result establishes conditions for the convergence of the cycles of (1.8) when the relaxation parameter  $\varepsilon$  vanishes.

**Theorem 2.8** Suppose that Assumptions 1.1 and 2.1 are satisfied. Then Fix  $T \neq \emptyset$ . Now let  $(x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[} = (z^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  be the bounded curve provided by (2.1) and denote by  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  the associated family of cycles arising from (1.8). Then  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  is bounded and each of its weak sequential cluster points is of the form  $(x, \ldots, x)$ , where  $x \in \text{Fix } T$ . Moreover,

$$(\forall i \in I) \quad \lim_{\varepsilon \to 0} \|x_i^\varepsilon - x_{i-1}^\varepsilon\| = 0, \quad where \quad (\forall \varepsilon \in ]0, \eta[) \quad x_0^\varepsilon = x_m^\varepsilon.$$

$$(2.9)$$

In addition, suppose that one of the following holds.

- (i)  $(\forall x \in \operatorname{Fix} T)(\forall y \in \operatorname{Fix} T) \langle x_m^{\varepsilon} | x y \rangle$  converges as  $\varepsilon \to 0$ .
- (ii)  $(\forall x \in \operatorname{Fix} T) ||x_m^{\varepsilon} x||$  converges as  $\varepsilon \to 0$ .
- (iii) Fix T is a singleton.

Then there exists  $\overline{x} \in \operatorname{Fix} T$  such that, for every  $i \in I$ ,  $x_i^{\varepsilon} \to \overline{x}$  as  $\varepsilon \to 0$ . Finally, suppose that  $\operatorname{Id} -T$  is demiregular on  $\operatorname{Fix} T$ , *i.e.*,

$$(\forall (y_k)_{k\in\mathbb{N}}\in D^{\mathbb{N}}) (\forall y\in\operatorname{Fix} T) \quad \begin{cases} y_k\rightharpoonup y\\ y_k-Ty_k\to 0 \end{cases} \Rightarrow y_k\to y.$$
 (2.10)

Then, for every  $i \in I$ ,  $x_i^{\varepsilon} \to \overline{x}$  as  $\varepsilon \to 0$ .

*Proof.* Fix  $z \in D$ . By nonexpansiveness of the operators  $(T_i)_{i \in I}$ , we have

$$(\forall i \in I) \quad \|T_i x_{i-1}^{\varepsilon} - x_{i-1}^{\varepsilon}\| \leq \|T_i x_{i-1}^{\varepsilon} - T_i z\| + \|T_i z - z\| + \|z - x_{i-1}^{\varepsilon}\| \\ \leq 2\|x_{i-1}^{\varepsilon} - z\| + \|T_i z - z\|.$$

$$(2.11)$$

In particular, for i = 1, it follows from the boundedness of  $(x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  that  $(T_1 x_m^{\varepsilon} - x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  is bounded. In turn, we deduce from (1.8) that  $(x_1^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  is bounded. Continuing this process, we obtain the boundedness of  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  and the fact that

$$(\forall i \in I) \quad (T_i x_{i-1}^{\varepsilon} - x_{i-1}^{\varepsilon})_{\varepsilon \in ]0,\eta[} \quad \text{is bounded.}$$

$$(2.12)$$

On the other hand, adding all the equalities in (1.8), we get

$$(\forall \varepsilon \in ]0, \eta[) \quad \sum_{i \in I} T_i x_{i-1}^{\varepsilon} = \sum_{i \in I} x_i^{\varepsilon}, \tag{2.13}$$

from which it follows that

$$(\forall \varepsilon \in ]0, \eta[) \quad Tx_m^{\varepsilon} - x_m^{\varepsilon} = \frac{1}{m} \sum_{i=1}^m T_i x_m^{\varepsilon} - x_m^{\varepsilon}$$
$$= \frac{1}{m} \sum_{i=1}^m T_i x_{i-1}^{\varepsilon} + \frac{1}{m} \sum_{i=2}^m \left( T_i x_m^{\varepsilon} - T_i x_{i-1}^{\varepsilon} \right) - x_m^{\varepsilon}$$
$$= \frac{1}{m} \sum_{i=1}^m x_i^{\varepsilon} + \frac{1}{m} \sum_{i=2}^m \left( T_i x_m^{\varepsilon} - T_i x_{i-1}^{\varepsilon} \right) - x_m^{\varepsilon}$$
$$= \frac{1}{m} \sum_{i=1}^{m-1} \left( x_i^{\varepsilon} - x_m^{\varepsilon} \right) + \frac{1}{m} \sum_{i=1}^{m-1} \left( T_{i+1} x_m^{\varepsilon} - T_{i+1} x_i^{\varepsilon} \right).$$
(2.14)

Hence, using the nonexpansiveness of the operators  $(T_i)_{i \in I}$ , we obtain

$$(\forall \varepsilon \in ]0, \eta[) \quad \|Tx_m^{\varepsilon} - x_m^{\varepsilon}\| \leq \frac{2}{m} \sum_{i=1}^{m-1} \|x_m^{\varepsilon} - x_i^{\varepsilon}\|.$$

$$(2.15)$$

Consequently, since (1.8) and (2.12) also imply that

$$(\forall i \in I) \quad \|x_i^{\varepsilon} - x_{i-1}^{\varepsilon}\| = \varepsilon \|T_i x_{i-1}^{\varepsilon} - x_{i-1}^{\varepsilon}\| \to 0 \quad \text{as} \quad \varepsilon \to 0,$$
(2.16)

thus proving (2.9), the triangle inequality gives  $||x_m^{\varepsilon} - x_i^{\varepsilon}|| \to 0$ , which, combined with (2.15), yields

$$Tx_m^{\varepsilon} - x_m^{\varepsilon} \to 0. \tag{2.17}$$

Hence, we can invoke the demiclosed principle [5, Corollary 4.18] to deduce that every weak sequential cluster point of the bounded curve  $(x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  belongs to Fix T, which is therefore nonempty. In view of (2.16), we therefore deduce that every weak sequential cluster point of  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  is of the form  $(x, \ldots, x)$ , where  $x \in \text{Fix } T$ . It remains to show that under any of the conditions (i), (ii), or (iii), the curve  $(x_m^{\varepsilon})_{\varepsilon \in ]0,1[}$  is weakly convergent. Clearly (iii) implies (i), and the same holds for (ii) since

$$(\forall (x,y) \in \mathcal{H}^2) (\forall \varepsilon \in ]0, \eta[) \quad \langle x_m^{\varepsilon} \mid x - y \rangle = \frac{1}{2} \big( \|x_m^{\varepsilon} - y\|^2 - \|x_m^{\varepsilon} - x\|^2 + \|x\|^2 - \|y\|^2 \big).$$
(2.18)

Thus, it suffices to show that under (i) the curve  $(x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  has a unique weak sequential cluster point. Let x and y be two weak sequential cluster points and choose sequences  $(\varepsilon_n)_{n\in\mathbb{N}}$  and  $(\varepsilon'_n)_{n\in\mathbb{N}}$  in  $]0,\eta[$  converging to 0 such that  $x_m^{\varepsilon_n} \rightharpoonup x$  and  $x_m^{\varepsilon'_n} \rightharpoonup y$  as  $n \rightarrow +\infty$ . As shown above, we have x and y lie in Fix T and, therefore, it follows from (i) that  $\langle x \mid x - y \rangle = \lim_{n \to +\infty} \langle x_m^{\varepsilon'_n} \mid x - y \rangle = \langle y \mid x - y \rangle$ . This yields  $||x - y||^2 = 0$  proving our claim.

Finally, let us establish the strong convergence assertion. To this end, let  $(\varepsilon_n)_{n\in\mathbb{N}}$  be a sequence in  $]0, \eta[$  converging to 0. Then, as just proved,  $x_m^{\varepsilon_n} \to \overline{x} \in \operatorname{Fix} T$  as  $n \to +\infty$ . On the other hand, (2.17) yields  $x_m^{\varepsilon_n} - Tx_m^{\varepsilon_n} \to 0$  as  $n \to +\infty$ . Hence, we derive from (2.10) that  $x_m^{\varepsilon_n} \to \overline{x}$  as  $n \to +\infty$ . This shows that  $x_m^{\varepsilon} \to \overline{x}$  as  $\varepsilon \to 0$ . In view of (2.16), the proof is complete.  $\Box$ 

**Remark 2.9** The demiregularity condition (2.10) is a specialization of a notion introduced in [1, Definition 2.3] for set-valued operators (see also [19, Definition 27.1]). It follows from [1, Proposition 2.4] that (2.10) is satisfied in each of the following cases.

- (i) Id -T is uniformly monotone at every  $y \in \operatorname{Fix} T$ .
- (ii) Id -T is strongly monotone at every  $y \in \operatorname{Fix} T$ .
- (iii) D is boundedly compact: its intersection with every closed ball is compact.
- (iv)  $D = \mathcal{H}$  and  $\mathrm{Id} T$  is invertible and continuous.
- (v) T is demicompact [17]: for every bounded sequence  $(y_n)_{n \in \mathbb{N}}$  in D such that  $(y_n Ty_n)_{n \in \mathbb{N}}$  converges strongly,  $(y_n)_{n \in \mathbb{N}}$  admits a strongly convergent subsequence.

In the special case when  $(T_i)_{i \in I}$  is a family of projection operators onto closed convex sets, Theorem 2.8 asserts that De Pierro's conjecture is true under any of conditions (i)–(iii). In particular, we obtain weak convergence of each point in the cycle to the point in Fix T if this set is a singleton, which is a common situation in many practical instances when  $\bigcap_{i \in I} \operatorname{Fix} T_i \neq \emptyset$ . The following example illustrates a degenerate case in which weak convergence of the cycles can fail.

**Example 2.10** Suppose that in Theorem 2.8 we have  $\bigcap_{i \in I} \operatorname{Fix} T_i \neq \emptyset$ . Then it follows from the results of [5, Section 4.5] that

$$(\forall \varepsilon \in ]0,1[) \quad \operatorname{Fix} R^{\varepsilon} = \bigcap_{i \in I} \operatorname{Fix} \left( (1-\varepsilon) \operatorname{Id} + \varepsilon T_i \right) = \bigcap_{i \in I} \operatorname{Fix} T_i = \operatorname{Fix} T.$$
(2.19)

Now suppose y and z are two distinct points in Fix T and set

$$(\forall \varepsilon \in ]0,1[) \quad x_m^{\varepsilon} = \begin{cases} y, & \text{if } \lfloor 1/\varepsilon \rfloor \text{ is even;} \\ z, & \text{if } \lfloor 1/\varepsilon \rfloor \text{ is odd.} \end{cases}$$
(2.20)

Then  $(x_m^{\varepsilon})_{\varepsilon \in ]0,1[}$  has two distinct weak cluster points and therefore it does not converge weakly, although Assumptions 1.1 and 2.1 are trivially satisfied.

## **3** Convergence of limit cycles of under-relaxed iterations

As illustrated in Example 2.10, in general one cannot expect every solution cycle  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$ in (1.8) to converge as there are cases that oscillate. Theorem 2.8 provided conditions that rule out multiple clustering and ensure the weak convergence of the cycles as  $\varepsilon \to 0$ . An alternative approach, inspired from [14], is to focus on solutions of (1.8) that arise as limit cycles of the under-relaxed periodic iteration (1.9) started from the same initial point  $y_0 \in D$  for every  $\varepsilon \in ]0, \eta[$ . This arbitrary but fixed initial point is intended to act as an anchor that avoids multiple cluster points of the resulting family of limit cycles  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in [0,n[}$ . As mentioned in the Introduction, for convex projection operators De Pierro conjectured that, as  $\varepsilon \to 0$ , the limit cycles shrink to a least-squares solution, namely  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon}) \rightharpoonup (\overline{x}, \ldots, \overline{x})$ , where  $\overline{x}$  is a minimizer of the function  $\Phi$  of (1.3). In [6, Theorem 6.4] the conjecture was proved for closed affine subspaces satisfying a regularity conditions, in which case the limit  $\overline{x}$  exists in the strong topology and is in fact the point in  $S = \operatorname{Argmin} \Phi = \operatorname{Fix} T$  closest to the initial point  $y_0$ , namely  $\overline{x} = P_S y_0$ . However, for general convex sets the conjecture remains open.

We revisit this question in the general framework delineated by Assumptions 1.1 and 2.1 with a different strategy than that adopted in Section 2. Our approach consists in showing that, for  $\varepsilon$  small, the iterates (1.9) follow closely the orbit of the semigroup generated by A = Id - T, i.e., the semigroup associated with the autonomous Cauchy problem

$$\begin{cases} \mathsf{u}'(t) = -A\mathsf{u}(t) \text{ on } ]0, +\infty[\\ \mathsf{u}(0) = y_0. \end{cases}$$
(3.1)

This allows us to relate the limit cycles  $(x_1^{\varepsilon}, \ldots, x_m^{\varepsilon})_{\varepsilon \in ]0,\eta[}$  to the limit of  $\mathbf{u}(t)$  when  $t \to +\infty$ . Note that, since  $y_0 \in D = \text{dom } A$  and A is Lipschitz, (3.1) has a unique solution  $\mathbf{u} \in \mathcal{C}^1(]0, +\infty[; D)$ ; see, e.g., [8, Theorem I.1.4]. In addition, if there exists  $x_{\infty} \in \mathcal{H}$  such that  $\mathbf{u}(t) \rightharpoonup x_{\infty}$  as  $t \to +\infty$ , then  $\overline{x} \in \text{Fix } T$ . In the case of convex projections, (3.1) reduces to the gradient flow

$$\begin{cases} \mathsf{u}'(t) = -\nabla \Phi(\mathsf{u}(t)) \text{ on } ]0, +\infty[\\ \mathsf{u}(0) = y_0, \end{cases}$$
(3.2)

which converges weakly to some point  $x_{\infty} \in S$  as  $t \to +\infty$  [9, Theorem 4], and one may therefore expect De Pierro's conjecture to hold with  $\overline{x} = x_{\infty}$  under suitable assumptions. Note, however, that for non-affine convex sets the limit  $x_{\infty}$  might not coincide with the projection  $P_S y_0$ .

### 3.1 Under-relaxed cyclic iterations and semigroup flows

In order to study (1.9) for a fixed  $\varepsilon \in [0, 1[$ , it suffices to consider the iterates modulo m, that is, the sequence  $(y_{km}^{\varepsilon})_{k\in\mathbb{N}} = ((R^{\varepsilon})^k y_0)_{k\in\mathbb{N}}$ , which converge weakly towards some point  $x_m^{\varepsilon} \in \text{Fix } R^{\varepsilon}$ (see Proposition 2.2). The key to establish a formal connection between the iteration (1.9) and the semigroup associated with (3.1), is the following approximation lemma that relates  $R^{\varepsilon}$  to A = Id - T.

**Lemma 3.1** Set A = Id - T, fix  $z \in D$ , and set  $\rho = \max_{i \in I} ||T_i z - z||/2$ . Then

$$(\forall \varepsilon \in [0,1])(\forall x \in D) \quad \|R^{\varepsilon}x - x + \varepsilon mAx\| \leq \varepsilon^2 (3^m - 2m - 1)(\|x - z\| + \rho).$$
(3.3)

*Proof.* Since the case  $\varepsilon = 0$  is trivial, we take  $\varepsilon \in [0, 1]$ . Define operators on D by

$$(\forall j \in I) \quad R_j^{\varepsilon} = \left( \operatorname{Id} + \varepsilon(T_j - \operatorname{Id}) \right) \circ \dots \circ \left( \operatorname{Id} + \varepsilon(T_1 - \operatorname{Id}) \right)$$
(3.4)

and

$$(\forall j \in I) \quad E_j^{\varepsilon} = \frac{1}{\varepsilon^2} (R_j^{\varepsilon} - \mathrm{Id}) + \frac{1}{\varepsilon} \sum_{i=1}^j (\mathrm{Id} - T_i).$$
(3.5)

Then  $R^{\varepsilon} = R_m^{\varepsilon}$  and therefore  $R^{\varepsilon} - \operatorname{Id} + \varepsilon mA = \varepsilon^2 E_m^{\varepsilon}$ . Thus, the result boils down to showing that  $(\forall x \in D) ||E_m^{\varepsilon} x|| \leq (3^m - 2m - 1)(||x - z|| + \rho)$ . We derive from (3.5) that

$$(\forall j \in \{1, \dots, m-1\}) \quad E_{j+1}^{\varepsilon} = E_j^{\varepsilon} + \frac{1}{\varepsilon} \Big( (\operatorname{Id} - T_{j+1}) - (\operatorname{Id} - T_{j+1}) \circ R_j^{\varepsilon} \Big). \tag{3.6}$$

Now let  $x \in D$ . Since the operators  $(\mathrm{Id} - T_j)_{1 \leq j \leq m-1}$  are 2-Lipschitz, we have

$$(\forall j \in \{1, \dots, m-1\}) \quad \|E_{j+1}^{\varepsilon}x\| \leq \|E_{j}^{\varepsilon}x\| + \frac{2}{\varepsilon}\|x - R_{j}^{\varepsilon}x\|$$
$$= \|E_{j}^{\varepsilon}x\| + 2\left\|\sum_{i=1}^{j}(\mathrm{Id} - T_{i})x - \varepsilon E_{j}^{\varepsilon}x\right\|$$
$$\leq (1+2\varepsilon)\|E_{j}^{\varepsilon}x\| + 2\sum_{i=1}^{j}(\|x-z\| + \|z - T_{i}z\| + \|T_{i}z - T_{i}x\|)$$
$$\leq (1+2\varepsilon)\|E_{j}^{\varepsilon}x\| + 4j(\|x-z\| + \rho). \tag{3.7}$$

Using (3.7) recursively, and observing that  $E_1^{\varepsilon} x = 0$ , it follows that

$$\|E_m^{\varepsilon}x\| \le 4(\|x-z\|+\rho) \sum_{j=1}^{m-1} j(1+2\varepsilon)^{m-1-j}.$$
(3.8)

Upon applying the identity  $\sum_{j=1}^{m-1} j\alpha^j = ((m-1)\alpha^{m+1} - m\alpha^m + \alpha)/(1-\alpha)^2$  to  $\alpha = (1+2\varepsilon)^{-1} \in [0,1[$ , we see that the sum in (3.8) is equal to  $((1+2\varepsilon)^m - 1 - 2m\varepsilon)/(4\varepsilon^2)$ , which increases with  $\varepsilon$  attaining its maximum  $(3^m - 2m - 1)/4$  at  $\varepsilon = 1$ . This combined with (3.8) yields the announced bound.  $\Box$ 

**Remark 3.2** For firmly nonexpansive operators, such as projection operators onto closed convex sets, the operators  $(\text{Id} - T_i)_{i \in I}$  are nonexpansive and the previous proof can be modified to derive a tighter bound in (3.3), namely

$$(\forall \varepsilon \in [0,1])(\forall x \in D) \quad \|R^{\varepsilon}x - x + \varepsilon mAx\| \leq \varepsilon^2 (2^m - m - 1)(\|x - z\| + 2\rho).$$
(3.9)

We proceed with the announced connection between (1.9) and (3.1). This will be used later to prove De Pierro's conjecture in several alternative settings.

**Proposition 3.3** Let  $y_0 \in D$ , let u be the solution of (3.1), suppose that Assumptions 1.1 and 2.1 are satisfied. For every  $\varepsilon \in ]0, \eta[$ , let  $u^{\varepsilon}$  be the linear interpolation of the sequence  $(u_k^{\varepsilon})_{k \in \mathbb{N}} = ((R^{\varepsilon})^k y_0)_{k \in \mathbb{N}}$ , namely

$$\left( \forall k \in \mathbb{N} \right) \left( \forall t \in [km\varepsilon, (k+1)m\varepsilon[) \quad \mathsf{u}^{\varepsilon}(t) = u_k^{\varepsilon} + \frac{t - km\varepsilon}{m\varepsilon} (u_{k+1}^{\varepsilon} - u_k^{\varepsilon}). \right)$$
(3.10)

Then  $(\forall \bar{t} \in ]0, +\infty[) \sup_{0 \leq t \leq \bar{t}} \| \mathsf{u}^{\varepsilon}(t) - \mathsf{u}(t) \| \to 0 \text{ when } \varepsilon \to 0.$ 

*Proof.* Set A = Id - T, let  $\varepsilon \in [0, \eta[$ , and fix  $z \in D$ . The function  $u^{\varepsilon}$  is differentiable except at the breakpoints  $\{km\varepsilon \mid k \in \mathbb{N}\}$ . Now set  $(\forall k \in \mathbb{N}) J_k = ]km\varepsilon, (k+1)m\varepsilon[$ . According to Lemma 3.1, we have

$$(\forall k \in \mathbb{N})(\forall t \in J_k) \quad (\mathbf{u}^{\varepsilon})'(t) = \frac{1}{m\varepsilon}(u_{k+1}^{\varepsilon} - u_k^{\varepsilon}) = \frac{1}{m\varepsilon}(R^{\varepsilon}u_k^{\varepsilon} - u_k^{\varepsilon}) = -Au_k^{\varepsilon} + \varepsilon h_k^{\varepsilon}, \qquad (3.11)$$

where  $\|h_k^{\varepsilon}\| \leq (3^m - 2m - 1)(\|u_k^{\varepsilon} - z\| + \rho)/m$ . Now set

$$(\forall k \in \mathbb{N})(\forall t \in J_k) \quad h^{\varepsilon}(t) = A \mathsf{u}^{\varepsilon}(t) - A u_k^{\varepsilon} + \varepsilon h_k^{\varepsilon}.$$
(3.12)

Then

$$(\forall k \in \mathbb{N})(\forall t \in J_k) \quad (\mathbf{u}^{\varepsilon})'(t) = -A\mathbf{u}^{\varepsilon}(t) + h^{\varepsilon}(t).$$
(3.13)

Moreover, it follows from (2.1) that there exists a constant  $\alpha \in [0, +\infty)$  independent from  $\varepsilon$  such that  $(\forall k \in \mathbb{N}) ||h_k^{\varepsilon}|| \leq \alpha$ . Hence, since A is 2-Lipschitz, there exists  $\gamma \in [0, +\infty)$  such that

$$(\forall k \in \mathbb{N})(\forall t \in J_k) \quad \|h^{\varepsilon}(t)\| \leq 2\|\mathbf{u}^{\varepsilon}(t) - u_k^{\varepsilon}\| + \varepsilon \|h_k^{\varepsilon}\| \\ \leq 2\|u_{k+1}^{\varepsilon} - u_k^{\varepsilon}\| + \varepsilon \|h_k^{\varepsilon}\| \\ = 2\varepsilon m\| - Au_k^{\varepsilon} + \varepsilon h_k^{\varepsilon}\| + \varepsilon \|h_k^{\varepsilon}\| \\ \leq \varepsilon \gamma.$$

$$(3.14)$$

Next, consider the function  $\theta: [0, +\infty[ \rightarrow [0, +\infty[$  defined by  $\theta(t) = ||\mathbf{u}(t) - \mathbf{u}^{\varepsilon}(t)||^2$ . Then it follows from the monotonicity of A that

$$(\forall t \in [0, +\infty[ \smallsetminus \{km\varepsilon \mid k \in \mathbb{N}\}) \quad \theta'(t) = 2\langle \mathsf{u}(t) - \mathsf{u}^{\varepsilon}(t) \mid \mathsf{u}'(t) - (\mathsf{u}^{\varepsilon})'(t) \rangle$$
$$= 2\langle \mathsf{u}(t) - \mathsf{u}^{\varepsilon}(t) \mid A\mathsf{u}^{\varepsilon}(t) - h^{\varepsilon}(t) - A\mathsf{u}(t) \rangle$$
$$\leq 2\langle \mathsf{u}(t) - \mathsf{u}^{\varepsilon}(t) \mid -h^{\varepsilon}(t) \rangle$$
$$\leq 2\|\mathsf{u}(t) - \mathsf{u}^{\varepsilon}(t)\| \|h^{\varepsilon}(t)\|$$
$$\leq 2\varepsilon\gamma\sqrt{\theta(t)}. \tag{3.15}$$

Integrating this inequality and noting that  $\theta(0) = 0$ , we obtain  $(\forall t \in [0, +\infty[) || \mathbf{u}^{\varepsilon}(t) - \mathbf{u}(t)|| = \sqrt{\theta(t)} \leq \varepsilon \gamma t$ . Now let  $\overline{t} \in ]0, +\infty[$ . Then  $\sup_{0 \leq t \leq \overline{t}} || \mathbf{u}^{\varepsilon}(t) - \mathbf{u}(t)|| \leq \varepsilon \gamma \overline{t} \to 0$  as  $\varepsilon \to 0$ .  $\square$ 

#### **3.2** Strong convergence under stability of approximate cycles

In this section, we investigate the strong convergence of the cycles defined in (1.8) when a stability condition holds.

**Theorem 3.4** Suppose that Assumptions 1.1 and 2.1 are satisfied, and that

$$(\forall z \in \operatorname{Fix} T) \quad \lim_{\varepsilon \to 0} d_{\operatorname{Fix} R^{\varepsilon}}(z) = 0.$$
 (3.16)

In addition, let  $y_0 \in D$ , and suppose that the orbit of  $y_0$  in the Cauchy problem (3.1) converges strongly, say  $\mathbf{u}(t) \to \overline{x} \in D$  as  $t \to +\infty$ . For every  $\varepsilon \in ]0, \eta[$ , let  $(x_i^{\varepsilon})_{i \in I}$  be the cycle obtained as the weak limit of (1.9) in Proposition 2.2. Then  $\overline{x} \in \operatorname{Fix} T$  and  $(\forall i \in I) \ x_i^{\varepsilon} \to \overline{x}$  when  $\varepsilon \to 0$ .

Proof. Since  $\mathbf{u}(t) \to \overline{x}$ , (3.1) implies that  $\mathbf{u}'(t)$  converges to  $A\overline{x}$  and therefore  $A\overline{x} = 0$  since  $\mathbf{u}'(t) \to 0$ . Hence,  $\overline{x} \in \text{Fix } T$ . Now fix  $\delta \in ]0, +\infty[$  and  $\overline{t} \in ]0, +\infty[$  such that  $(\forall t \in [\overline{t}, +\infty[) \| \mathbf{u}(t) - \overline{x} \| \leq \delta$ . For every  $\varepsilon \in ]0, \eta[$ , set  $(u_k^{\varepsilon})_{k \in \mathbb{N}} = (y_{km}^{\varepsilon})_{k \in \mathbb{N}} = ((R^{\varepsilon})^k y_0)_{k \in \mathbb{N}}$  and define the function  $\mathbf{u}^{\varepsilon}$  as in (3.10). By Proposition 3.3, there exists  $\varepsilon_0 \in ]0, \eta[$  such that

$$(\forall \varepsilon \in ]0, \varepsilon_0[)(\forall t \in [0, \bar{t} + m]) \quad \|\mathbf{u}^{\varepsilon}(t) - \mathbf{u}(t)\| \leqslant \delta.$$
(3.17)

Now let  $\varepsilon \in [0, \varepsilon_0[$ , choose  $k_0 \in \mathbb{N}$  such that  $k_0 m \varepsilon \in [\bar{t}, \bar{t} + m]$ , and set  $\bar{x}^{\varepsilon} = P_{\text{Fix} R^{\varepsilon}} \bar{x}$  (recall that, since D is closed and convex and  $R^{\varepsilon}$  is nonexpansive, Fix  $R^{\varepsilon}$  is closed and convex [5, Corollary 4.15]). Thus  $\|u_{k_0}^{\varepsilon} - u(k_0 m \varepsilon)\| = \|u^{\varepsilon}(k_0 m \varepsilon) - u(k_0 m \varepsilon)\| \leq \delta$  and then  $\|u_{k_0}^{\varepsilon} - \bar{x}\| \leq 2\delta$ . Since  $R^{\varepsilon}$  is nonexpansive, we have  $(\forall k \in \mathbb{N}) \|u_{k+1}^{\varepsilon} - \bar{x}^{\varepsilon}\| \leq \|u_k^{\varepsilon} - \bar{x}^{\varepsilon}\|$ . Hence, for every integer  $k \geq k_0$ , we have

$$\|u_k^{\varepsilon} - \bar{x}^{\varepsilon}\| \leqslant \|u_{k_0}^{\varepsilon} - \bar{x}^{\varepsilon}\| \leqslant \|u_{k_0}^{\varepsilon} - \bar{x}\| + \|\bar{x} - \bar{x}^{\varepsilon}\| \leqslant 2\delta + d_{\operatorname{Fix} R^{\varepsilon}}(\bar{x})$$
(3.18)

and therefore

$$\|y_{km}^{\varepsilon} - \overline{x}\| = \|u_k^{\varepsilon} - \overline{x}\| \leq 2\delta + 2d_{\operatorname{Fix} R^{\varepsilon}}(\overline{x}).$$
(3.19)

Since Proposition 2.2 asserts that  $y_{km}^{\varepsilon} \rightharpoonup x_m^{\varepsilon}$ , we get

$$\|x_m^{\varepsilon} - \overline{x}\| \leq \lim_{k \to +\infty} \|y_{km}^{\varepsilon} - \overline{x}\| \leq 2\delta + 2d_{\operatorname{Fix} R^{\varepsilon}}(\overline{x}),$$
(3.20)

and (3.16) yields

$$\overline{\lim_{\varepsilon \to 0}} \|x_m^{\varepsilon} - \overline{x}\| \leqslant 2\delta.$$
(3.21)

Letting  $\delta \to 0$ , we deduce that  $x_m^{\varepsilon} \to \overline{x}$  as  $\varepsilon \to 0$ . In turn, it follows from (2.9) that  $(\forall i \in I)$  $x_i^{\varepsilon} \to \overline{x}$  as  $\varepsilon \to 0$ .  $\square$ 

The following corollary settles entirely De Pierro's conjecture in the case of m = 2 closed convex sets in Euclidean spaces.

**Corollary 3.5** In Assumption 1.1, suppose that  $\mathcal{H}$  is finite-dimensional,  $D = \mathcal{H}$ , and m = 2, and let  $T_1 = P_1$  and  $T_2 = P_2$  be the projection operators onto nonempty closed convex sets such that

Fix 
$$T = S = \operatorname{Argmin} \Phi \neq \emptyset$$
, where  $\Phi = \frac{1}{4} (d_{C_1}^2 + d_{C_2}^2)$ . (3.22)

Let  $y_0 \in \mathcal{H}$  and let  $\overline{x} \in S$  be the limit of the solution u of the Cauchy problem

$$\begin{cases} \mathsf{u}'(t) + \mathsf{u}(t) = \frac{1}{2} \big( P_1 \mathsf{u}(t) + P_2 \mathsf{u}(t) \big) & on \ ]0, +\infty[ \\ \mathsf{u}(0) = y_0. \end{cases}$$
(3.23)

For for every  $\varepsilon \in [0,1[$ , let  $x_1^{\varepsilon} = \lim_{k \to +\infty} y_{2k+1}^{\varepsilon}$  and  $x_2^{\varepsilon} = \lim_{k \to +\infty} y_{2k+2}^{\varepsilon}$ , where

$$(\forall k \in \mathbb{N}) \qquad \begin{cases} y_{2k+1}^{\varepsilon} &= (\operatorname{Id} + \varepsilon (P_1 - \operatorname{Id})) y_{2k}^{\varepsilon} \\ y_{2k+2}^{\varepsilon} &= (\operatorname{Id} + \varepsilon (P_2 - \operatorname{Id})) y_{2k+1}^{\varepsilon}. \end{cases}$$
(3.24)

Then  $x_1^{\varepsilon} \to \overline{x}$  and  $x_2^{\varepsilon} \to \overline{x}$  when  $\varepsilon \to 0$ .

*Proof.* Fix  $z \in S$ , and set  $a = P_1 z$  and  $b = P_2 z$ . Then z = (a + b)/2 and  $(\forall \varepsilon \in ]0,1[)$  $z^{\varepsilon} = ((1 - \varepsilon)a + b)/(2 - \varepsilon) \in \text{Fix } R^{\varepsilon}$ . Thus

$$d_{\operatorname{Fix} R^{\varepsilon}}(z) \leqslant ||z - z^{\varepsilon}|| = \frac{\varepsilon ||b - a||}{2(2 - \varepsilon)} \to 0 \quad \text{as} \quad \varepsilon \to 0,$$
(3.25)

and the conclusion follows from Theorem 3.4.  $\square$ 

We conclude this section by showing that, in contrast with (3.25), the condition (3.16) can fail in the case of projection operators in the presence of m = 3 sets.

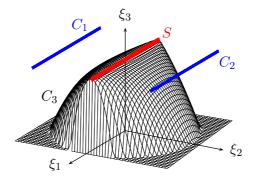


Figure 2: An example in which the condition (3.16) fails.

**Example 3.6** Suppose that  $\mathcal{H} = \mathbb{R}^3$  and m = 3, and let  $T_1$ ,  $T_2$ , and  $T_3$  be, respectively, the projection operators onto the bounded closed convex sets (see Fig. 2)

$$\begin{cases} C_1 = [-1,1] \times \{-1\} \times \{1\} \\ C_2 = [-1,1] \times \{1\} \times \{1\} \\ C_3 = \{(\xi_1,\xi_2,\xi_3) \in \mathbb{R}^3 \mid \xi_1 \in [-1,1], \, \xi_3 \in [0,1], \, (1-\xi_3)(\xi_1^2-1) + \xi_2^2 \leqslant 0\}. \end{cases}$$
(3.26)

Then the set of least-squares solutions is  $S = \operatorname{Fix} T = [-1, 1] \times \{0\} \times \{1\} \subset C_3$ . Moreover,

$$(\forall \varepsilon \in ]0,1[) \quad \text{Fix} \, R^{\varepsilon} = \{z^{\varepsilon}\} = \left\{ \left(0, \frac{w_{\varepsilon} + \varepsilon(1-\varepsilon)}{3(1-\varepsilon) + \varepsilon^2}, 1 - \frac{w_{\varepsilon}^2}{3(1-\varepsilon) + \varepsilon^2}\right) \right\},\tag{3.27}$$

where  $w_{\varepsilon}$  is the unique real solution of  $2w^3 + w = \varepsilon/(2-\varepsilon)$ . Clearly  $z^{\varepsilon} \to (0,0,1) \in S$  as  $\varepsilon \to 0$ , but  $(\forall z \in S \setminus \{(0,0,1)\}) d_{\operatorname{Fix} R^{\varepsilon}}(z) \not\to 0$  as  $\varepsilon \to 0$ .

### 3.3 Strong convergence under local strong monotonicity

Another situation covered by Theorem 3.4 is when the operator T has a unique fixed point  $\overline{x}$  and A = Id - T is locally strongly monotone around  $\overline{x}$ , namely

$$(\exists \alpha \in ]0, +\infty[)(\exists \delta \in ]0, +\infty[)(\forall x \in D \cap B(\overline{x}; \delta)) \quad \langle x - \overline{x} \mid x - Tx \rangle \ge \alpha ||x - \overline{x}||^2.$$
(3.28)

In the case of convex projections operators, then  $A = \nabla \Phi$  and, if  $\Phi$  is twice differentiable at  $\overline{x}$ , then (3.28) is equivalent to the positive-definiteness of  $\nabla^2 \Phi(\overline{x})$ . Another case in which (3.28) is satisfied, with  $\alpha = 1 - \rho$ , is when T is a local strict contraction with constant  $\rho \in ]0, 1[$  at the fixed point  $\overline{x}$ , namely, for all x in some ball  $B(\overline{x}; \delta)$ ,  $||Tx - T\overline{x}|| \leq \rho ||x - \overline{x}||$ . If T is differentiable at  $\overline{x}$  this amounts to  $||T'(\overline{x})|| < 1$ .

**Theorem 3.7** Suppose that Assumptions 1.1 and 2.1 are satisfied, together with (3.28), and let Fix  $T = \{\bar{x}\}$ . In addition, let  $y_0 \in D$  and, for every  $\varepsilon \in ]0, \eta[$ , let  $(x_i^{\varepsilon})_{i \in I}$  be the cycle obtained as the weak limit of (1.9) in Proposition 2.2. Then  $(\forall i \in I) \ x_i^{\varepsilon} \to \bar{x} \ as \ \varepsilon \to 0$ .

*Proof.* It suffices to check the assumptions of Theorem 3.4. Set A = Id - T and let x be the solution to (3.1).

•  $d_{\operatorname{Fix} R^{\varepsilon}}(\overline{x}) \to 0 \text{ as } \varepsilon \to 0$ :

Let  $\varepsilon \in [0, \min\{\eta, \alpha/(2m)\}[$ , set  $Q^{\varepsilon} = \operatorname{Id} - m\varepsilon A$  and  $\gamma(\varepsilon) = 1 - m\varepsilon(\alpha - 2m\varepsilon)$ , and let  $y \in D \cap B(\overline{x}; \delta)$ . Since  $A\overline{x} = 0$  and A is 2-Lipschitz, we have

$$\begin{aligned} |Q^{\varepsilon}y - \overline{x}||^{2} &= \|y - \overline{x}\|^{2} - 2m\varepsilon\langle y - \overline{x} \mid Ay - A\overline{x}\rangle + (m\varepsilon)^{2}\|Ay - A\overline{x}\|^{2} \\ &\leq (1 - 2m\varepsilon(\alpha - 2m\varepsilon))\|y - \overline{x}\|^{2} \\ &\leq \gamma(\varepsilon)^{2}\|y - \overline{x}\|^{2}. \end{aligned}$$
(3.29)

On the other hand, setting  $\rho = \max_{i \in I} ||T_i \overline{x} - \overline{x}||/2$  and  $\beta = 3^m - 2m - 1$ , Lemma 3.1 gives

$$\|R^{\varepsilon}y - Q^{\varepsilon}y\| \leqslant \varepsilon^{2}\beta(\|y - \overline{x}\| + \rho)$$
(3.30)

which, combined with (3.29), yields

$$\|R^{\varepsilon}y - \overline{x}\| \leq \|R^{\varepsilon}y - Q^{\varepsilon}y\| + \|Q^{\varepsilon}y - \overline{x}\| \leq \varepsilon^{2}\beta(\|y - \overline{x}\| + \rho) + \gamma(\varepsilon)\|y - \overline{x}\|.$$
(3.31)

From this estimate it follows that given  $\delta' \in [0, \delta]$ , for every  $\varepsilon \leq m\alpha\delta'/(\beta(\delta' + \rho) + 2m^2\delta')$ we have  $R^{\varepsilon}(D \cap B(\overline{x}; \delta')) \subset D \cap B(\overline{x}; \delta')$ . Hence  $R^{\varepsilon}$  has a fixed point in  $B(\overline{x}; \delta')$  and hence  $d_{\text{Fix}R^{\varepsilon}}(\overline{x}) \leq \delta'$ . Since  $\delta'$  can be arbitrarily small, this proves that  $d_{\text{Fix}R^{\varepsilon}}(\overline{x}) \to 0$  as  $\varepsilon \to 0$ .

•  $u(t) \to \overline{x} \text{ as } t \to +\infty$ :

Let  $\theta: [0, +\infty[ \to [0, +\infty[$  be defined by  $\theta(t) = ||\mathbf{u}(t) - \overline{x}||^2/2$ , and let us show that  $\lim_{t\to+\infty} \theta(t) = 0$ . We note that this holds whenever the orbit enters the ball  $B(\overline{x}; \delta)$  at some instant  $t_0$ . Indeed, the monotonicity of A implies that  $\theta$  is decreasing so that, for every  $t \in [t_0, +\infty[$ ,  $\mathbf{u}(t) \in D \cap B(\overline{x}; \delta)$  and hence (3.1) and (3.28) give

$$\theta'(t) = \left\langle \mathsf{u}(t) - \overline{x} \mid \mathsf{u}'(t) \right\rangle = \left\langle \overline{x} - \mathsf{u}(t) \mid \mathsf{u}(t) - T\mathsf{u}(t) \right\rangle \leqslant -\alpha \|\mathsf{u}(t) - \overline{x}\|^2 = -2\alpha\theta(t).$$
(3.32)

Consequently,  $\theta(t) \leq \theta(t_0) \exp(-2\alpha(t-t_0)) \to 0$  as  $t \to +\infty$ . It remains to prove that u(t) enters the ball  $B(\overline{x}; \delta)$ . If this was not the case we would have  $\mu = \lim_{t \to +\infty} \sqrt{2\theta(t)} \geq \delta$ . Choose  $t_0$  large enough so that  $\sqrt{2\theta(t_0)} \leq \mu + \delta/2$  and let  $\tilde{u}$  be the solution to the Cauchy problem

$$\begin{cases} \tilde{\mathbf{u}}'(t) = -A\tilde{\mathbf{u}}(t) \text{ on } [t_0, +\infty[\\ \tilde{\mathbf{u}}(t_0) = \tilde{x}_0, \end{cases}$$
(3.33)

where  $\tilde{x}_0 = \overline{x} + \delta(\mathsf{u}(t_0) - \overline{x})/||\mathsf{u}(t_0) - \overline{x}|| \in D \cap B(\overline{x}; \delta)$ . By monotonicity of  $A, t \mapsto ||\mathsf{u}(t) - \tilde{\mathsf{u}}(t)||$  is decreasing and hence

$$(\forall t \in [t_0, +\infty[) \quad \|\mathbf{u}(t) - \overline{x}\| \leq \|\mathbf{u}(t) - \tilde{\mathbf{u}}(t)\| + \|\tilde{\mathbf{u}}(t) - \overline{x}\| \\ \leq \|\mathbf{u}(t_0) - \tilde{\mathbf{u}}(t_0)\| + \|\tilde{\mathbf{u}}(t) - \overline{x}\| \\ \leq (\mu - \delta/2) + \|\tilde{\mathbf{u}}(t) - \overline{x}\|.$$

$$(3.34)$$

Since by the previous argument  $\|\tilde{u}(t) - \overline{x}\| \to 0$ , we reach a contradiction with the fact that  $(\forall t \in [0, +\infty[) \| u(t) - \overline{x}\| \ge \mu$ .

Altogether, the conclusion follows from Theorem 3.4.  $\Box$ 

**Remark 3.8** If Id -T were globally (rather than just locally as in (3.28)) strongly monotone at every point in Fix T, we could derive Theorem 3.7 directly from Theorem 2.8 and Remark 2.9(ii).

Theorem 3.7 can also be applied when the local strong monotonicity or the local contraction properties hold up to an affine subspace (see (3.35) below). This is relevant in the case studied in [6] when  $(T_i)_{i \in I}$  is a family of projection operators onto closed affine subspaces  $(x_i + E_i)_{i \in I}$ , where  $(E_i)_{i \in I}$  is a family of closed vector subspaces of  $\mathcal{H}$ , and more generally for unbounded closed convex cylinders of the form  $(B_i + E_i)_{i \in I}$ , where  $B_i$  is a nonempty bounded closed convex subset of  $E_i^{\perp}$ .

**Corollary 3.9** Suppose that Assumptions 1.1 and 2.1 are satisfied, that  $D = \mathcal{H}$ , and that  $(T_i)_{i \in I}$  is a family of projection operators onto nonempty closed convex subsets  $(C_i)_{i \in I}$  of  $\mathcal{H}$ . In addition, suppose that the set S of minimizers of  $\Phi$  in (1.3) is a closed affine subspace, say S = z + E, where  $z \in \mathcal{H}$  and E is a closed vector subspace of  $\mathcal{H}$ . Let  $y_0 \in D$ , set  $\overline{x} = P_S y_0$ , and, for every  $\varepsilon \in ]0, \eta[$ , let  $(x_i^{\varepsilon})_{i \in I}$  be the cycle obtained as the weak limit of (1.9) in Proposition 2.2. Then the following hold.

- (i)  $(\forall i \in I) x_i^{\varepsilon} \rightharpoonup \overline{x} \text{ as } \varepsilon \to 0.$
- (ii) Suppose that

$$(\forall y \in S)(\exists \rho \in [0,1[)(\exists \delta \in ]0, +\infty[)(\forall x \in B(0;\delta) \cap E^{\perp}) ||T(x+y) - Ty|| \leq \rho ||x||. (3.35)$$
  
Then  $(\forall i \in I) x_i^{\varepsilon} \to \overline{x} \text{ as } \varepsilon \to 0.$ 

Proof. Let  $i \in I$ . Since S = z + E, we have  $C_i + E \subset C_i$  and the iterates  $(y_k^{\varepsilon})_{k \in \mathbb{N}}$  in (1.9) move parallel to  $E^{\perp}$  and remain in  $y_0 + E^{\perp}$ . Hence, since  $\{\overline{x}\} = S \cap (y_0 + E^{\perp})$ , (i) follows by applying Theorem 2.8 in the space  $y_0 + E^{\perp}$ , while (ii) follows by applying Theorem 3.7 in this same space.  $\Box$ 

We conclude the paper by revisiting De Pierro's conjecture in the affine setting investigated in [6]. More precisely, we shall derive an alternative proof of the main result of [6] from Corollary 3.9. For this purpose, we recall the following notion of regularity.

**Definition 3.10** A finite family  $(E_i)_{i \in I}$  of closed vector subspaces of  $\mathcal{H}$  with intersection E is regular if

$$\left(\forall (y_k)_{n\in\mathbb{N}}\in\mathcal{H}^{\mathbb{N}}\right) \quad \max_{i\in I} d_{E_i}(y_k)\to 0 \quad \Rightarrow \quad d_E(y_k)\to 0. \tag{3.36}$$

**Theorem 3.11** Let  $(E_i)_{i\in I}$  be a regular family of closed vector subspaces of  $\mathcal{H}$  with intersection E and for, every  $i \in I$ , let  $\overline{x}_i \in \mathcal{H}$  and let  $P_i$  be the projection operator onto the affine subspace  $C_i = \overline{x}_i + E_i$ . Let  $y_0 \in \mathcal{H}$  and set  $S = \operatorname{Argmin} \sum_{i \in I} d_{C_i}^2$ . Then there exists  $z \in \mathcal{H}$  such that S = z + E. Moreover, for every  $\varepsilon \in [0, 1]$ , the cycle  $(x_i^{\varepsilon})_{i \in I}$  obtained as the weak limit of (1.9) in Proposition 2.2 exists, and  $(\forall i \in I) \ x_i^{\varepsilon} \to P_S y_0 \ as \varepsilon \to 0$ .

Proof. We have  $(\forall i \in I) P_i: x \mapsto \overline{x}_i + P_{E_i}(x - \overline{x}_i)$ . Hence Tx = a + Lx, where  $a = (1/m) \sum_{i \in I} (\overline{x}_i - P_{E_i}\overline{x}_i)$  and  $L = (1/m) \sum_{i \in I} P_{E_i}$ . According to [6, Theorem 5.4], the subspaces  $(E_i)_{i \in I}$  are regular if and only if  $\rho = ||L \circ P_{E^{\perp}}|| < 1$ , which implies that T is a strict contraction on  $y_0 + E^{\perp}$ . From this we get simultaneously that T has a fixed point z, that the least-squares solution set is of the form S = z + E, and that (3.35) holds. Hence, the result will follow from Corollary 3.9 provided that  $(x_i^{\varepsilon})_{i \in I}$  exists for every  $\varepsilon \in [0, 1]$ . This was proved in [6, Theorem 5.6] by noting that  $R^{\varepsilon}|_{y_0 + E^{\perp}}$  is a strict contraction. Indeed,  $R^{\varepsilon}$  is a composition of affine maps and an inductive

calculation reveals that it can be written as  $R^{\varepsilon}x = a^{\varepsilon} + L^{\varepsilon}x$ , where  $a^{\varepsilon} \in \mathcal{H}$  and  $L^{\varepsilon}$  is a linear operator which is a convex combination of nonexpansive linear maps, one of which is the strict contraction  $L \circ P_{E^{\perp}}$ .  $\square$ 

**Remark 3.12** Corollary 3.9(i) seems to be new even for affine subspaces  $(C_i)_{i \in I}$ . Also new in Corollary 3.9(ii) is the fact that strong convergence holds for more general convex sets than just translates of regular subspaces.

Acknowledgement. The research of P. L. Combettes was supported in part by the European Union under the 7th Framework Programme "FP7-PEOPLE-2010-ITN", grant agreement number 264735-SADCO. The research of R. Cominetti was supported by Fondecyt 1130564 and Núcleo Milenio Información y Coordinación en Redes ICM/FIC P10-024F.

## References

- H. Attouch, L. M. Briceño-Arias, and P. L. Combettes, A parallel splitting method for coupled monotone inclusions, SIAM J. Control Optim., vol. 48, pp. 3246–3270, 2010.
- [2] J.-B. Baillon, P. L. Combettes, and R. Cominetti, There is no variational characterization of the cycles in the method of periodic projections, J. Funct. Anal., vol. 262, pp. 400–408, 2012.
- [3] H. H. Bauschke and J. M. Borwein, On the convergence of von Neumann's alternating projection algorithm for two sets, *Set-Valued Anal.*, vol. 1, pp. 185–212, 1993.
- [4] H. H. Bauschke, R. Burachik, P. L. Combettes, V. Elser, D. R. Luke, H. Wolkowicz, Eds., Fixed-Point Algorithms for Inverse Problems in Science and Engineering. Springer-Verlag, New York, 2011.
- [5] H. H. Bauschke and P. L. Combettes, Convex Analysis and Monotone Operator Theory in Hilbert Spaces. Springer, New York, 2011.
- [6] H. H. Bauschke and M. R. Edwards, A conjecture by De Pierro is true for translates of regular subspaces, J. Nonlinear Convex Anal., vol. 6, pp. 93–116, 2005.
- [7] H. H. Bauschke, X. Wang, and C. J. S. Wylie, Fixed points of averages of resolvents: Geometry and algorithms, SIAM J. Optim., vol. 22, pp. 24–40, 2012.
- [8] H. Brézis, Opérateurs Maximaux Monotones et Semi-Groupes de Contractions dans les Espaces de Hilbert. North-Holland/Elsevier, New York, 1973.
- [9] R. E. Bruck, Asymptotic convergence of nonlinear contraction semigroups in Hilbert space, J. Funct. Anal., vol. 18, pp. 15–26, 1975.
- [10] C. L. Byrne, Applied Iterative Methods. A. K. Peters, Wellesley, MA, 2008.
- [11] A. Cegielski, Iterative Methods for Fixed Point Problems in Hilbert Spaces, Lecture Notes in Mathematics, vol. 2057. Springer, Heidelberg, 2012.
- [12] Y. Censor, P. P. B. Eggermont, and D. Gordon, Strong under-relaxation in Kaczmarz's method for inconsistent systems, *Numer. Math.*, vol. 41, pp. 83–92, 1983.

- [13] P. L. Combettes, Inconsistent signal feasibility problems: Least-squares solutions in a product space, IEEE Trans. Signal Process., vol. 42, pp. 2955–2966, 1994.
- [14] A. R. De Pierro, From parallel to sequential projection methods and vice versa in convex feasibility: Results and conjectures, in: D. Butnariu, Y. Censor, and S. Reich (Eds.), *Inherently Parallel* Algorithms for Feasibility and Optimization, pp. 187–201. Elsevier, New York, 2001.
- [15] A. R. De Pierro and A. N. Iusem, A parallel projection method for finding a common point of a family of convex sets, *Pesquisa Operacional*, vol. 5, pp. 1–20, 1985.
- [16] L. G. Gubin, B. T. Polyak, and E. V. Raik, The method of projections for finding the common point of convex sets, *Comput. Math. Math. Phys.*, vol. 7, pp. 1–24, 1967.
- [17] W. V. Petryshyn, Construction of fixed points of demicompact mappings in Hilbert space, J. Math. Anal. Appl., vol. 14, pp. 276–284, 1966.
- [18] X. Wang and H. H. Bauschke, Compositions and averages of two resolvents: Relative geometry of fixed points sets and a partial answer to a question by C. Byrne, *Nonlinear Anal.*, vol. 74, pp. 4550–4572, 2011.
- [19] E. Zeidler, Nonlinear Functional Analysis and Its Applications II/B, Springer-Verlag, New York, 1990.