

Heinz H. Bauschke Patrick L. Combettes Canadian Mathematical Society Société mathématique du Canada

Convex Analysis and Monotone Operator Theory in Hilbert Spaces



Foreword

This self-contained book offers a modern unifying presentation of three basic areas of nonlinear analysis, namely convex analysis, monotone operator theory, and the fixed point theory of nonexpansive mappings.

This turns out to be a judicious choice. Showing the rich connections and interplay between these topics gives a strong coherence to the book. Moreover, these particular topics are at the core of modern optimization and its applications.

Choosing to work in Hilbert spaces offers a wide range of applications, while keeping the mathematics accessible to a large audience. Each topic is developed in a self-contained fashion, and the presentation often draws on recent advances.

The organization of the book makes it accessible to a large audience. Each chapter is illustrated by several exercises, which makes the monograph an excellent textbook. In addition, it offers deep insights into algorithmic aspects of optimization, especially splitting algorithms, which are important in theory and applications.

Let us point out the high quality of the writing and presentation. The authors combine an uncompromising demand for rigorous mathematical statements and a deep concern for applications, which makes this book remarkably accomplished.

Montpellier (France), October 2010

Hédy Attouch

Preface

Three important areas of nonlinear analysis emerged in the early 1960s: convex analysis, monotone operator theory, and the theory of nonexpansive mappings. Over the past four decades, these areas have reached a high level of maturity, and an increasing number of connections have been identified between them. At the same time, they have found applications in a wide array of disciplines, including mechanics, economics, partial differential equations, information theory, approximation theory, signal and image processing, game theory, optimal transport theory, probability and statistics, and machine learning.

The purpose of this book is to present a largely self-contained account of the main results of convex analysis, monotone operator theory, and the theory of nonexpansive operators in the context of Hilbert spaces. Authoritative monographs are already available on each of these topics individually. A novelty of this book, and indeed, its central theme, is the tight interplay among the key notions of convexity, monotonicity, and nonexpansiveness. We aim at making the presentation accessible to a broad audience, and to reach out in particular to the applied sciences and engineering communities, where these tools have become indispensable. We chose to cast our exposition in the Hilbert space setting. This allows us to cover many applications of interest to practitioners in infinite-dimensional spaces and yet to avoid the technical difficulties pertaining to general Banach space theory that would exclude a large portion of our intended audience. We have also made an attempt to draw on recent developments and modern tools to simplify the proofs of key results, exploiting for instance heavily the concept of a Fitzpatrick function in our exposition of monotone operators, the notion of Fejér monotonicity to unify the convergence proofs of several algorithms, and that of a proximity operator throughout the second half of the book.

The book in organized in 29 chapters. Chapters 1 and 2 provide background material. Chapters 3 to 7 cover set convexity and nonexpansive operators. Various aspects of the theory of convex functions are discussed in Chapters 8 to 19. Chapters 20 to 25 are dedicated to monotone operator the-

x Preface

ory. In addition to these basic building blocks, we also address certain themes from different angles in several places. Thus, optimization theory is discussed in Chapters 11, 19, 26, and 27. Best approximation problems are discussed in Chapters 3, 19, 27, 28, and 29. Algorithms are also present in various parts of the book: fixed point and convex feasibility algorithms in Chapter 5, proximal-point algorithms in Chapter 23, monotone operator splitting algorithms in Chapter 25, optimization algorithms in Chapter 27, and best approximation algorithms in Chapters 27 and 29. More than 400 exercises are distributed throughout the book, at the end of each chapter.

Preliminary drafts of this book have been used in courses in our institutions and we have benefited from the input of postdoctoral fellows and many students. To all of them, many thanks. In particular, HHB thanks Liangjin Yao for his helpful comments. We are grateful to Hédy Attouch, Jon Borwein, Stephen Simons, Jon Vanderwerff, Shawn Wang, and Isao Yamada for helpful discussions and pertinent comments. PLC also thanks Oscar Wesler. Finally, we thank the Natural Sciences and Engineering Research Council of Canada, the Canada Research Chair Program, and France's Agence Nationale de la Recherche for their support.

Kelowna (Canada) Paris (France) October 2010 Heinz H. Bauschke Patrick L. Combettes

Contents

1	Bac	kground	1
	1.1	Sets in Vector Spaces	1
	1.2	Operators	2
	1.3	Order	3
	1.4	Nets	4
	1.5	The Extended Real Line	4
	1.6	Functions	5
	1.7	Topological Spaces	7
	1.8	Two-Point Compactification of the Real Line	9
	1.9	Continuity	9
	1.10	Lower Semicontinuity	10
		Sequential Topological Notions	15
	1.12	Metric Spaces	16
	Exer	rcises	22
2	Hilk	pert Spaces	27
	2.1	Notation and Examples	27
	2.2	Basic Identities and Inequalities	29
	2.3	Linear Operators and Functionals	31
	2.4	Strong and Weak Topologies	33
	2.5	Weak Convergence of Sequences	36
	2.6	Differentiability	37
	Exer	rcises	40
3	Con	ivex Sets	43
	3.1	Definition and Examples	43
	3.2	Best Approximation Properties	44
	3.3	Topological Properties	52
	3.4	Separation	55
	Exer	rcises	

xii Contents

4	Convexity and Nonexpansiveness 59
	4.1 Nonexpansive Operators
	4.2 Projectors onto Convex Sets
	4.3 Fixed Points of Nonexpansive Operators
	4.4 Averaged Nonexpansive Operators 67
	4.5 Common Fixed Points
	Exercises
5	Fejér Monotonicity and Fixed Point Iterations
	5.1 Fejér Monotone Sequences
	5.2 Krasnosel'skiĭ–Mann Iteration
	5.3 Iterating Compositions of Averaged Operators 82
	Exercises
6	Convex Cones and Generalized Interiors
	6.1 Convex Cones
	6.2 Generalized Interiors
	6.3 Polar and Dual Cones
	6.4 Tangent and Normal Cones
	6.5 Recession and Barrier Cones
	Exercises
7	Support Functions and Polar Sets
	7.1 Support Points
	7.2 Support Functions
	7.3 Polar Sets
	Exercises
8	Convex Functions
	8.1 Definition and Examples
	8.2 Convexity-Preserving Operations
	8.3 Topological Properties
	Exercises
9	Lower Semicontinuous Convex Functions
	9.1 Lower Semicontinuous Convex Functions
	9.2 Proper Lower Semicontinuous Convex Functions 132
	9.3 Affine Minorization
	9.4 Construction of Functions in $\Gamma_0(\mathcal{H})$
	Exercises
10	Convex Functions: Variants
	10.1 Between Linearity and Convexity
	10.2 Uniform and Strong Convexity
	10.3 Quasiconvexity
	Exercises

Contents xiii

11	Convex Variational Problems	155
	11.1 Infima and Suprema	155
	11.2 Minimizers	
	11.3 Uniqueness of Minimizers	157
	11.4 Existence of Minimizers	
	11.5 Minimizing Sequences	160
	Exercises	164
12	Infimal Convolution	167
	12.1 Definition and Basic Facts	167
	12.2 Infimal Convolution of Convex Functions	170
	12.3 Pasch–Hausdorff Envelope	172
	12.4 Moreau Envelope	173
	12.5 Infimal Postcomposition	178
	Exercises	
13	Conjugation	181
	13.1 Definition and Examples	
	13.2 Basic Properties	
	13.3 The Fenchel–Moreau Theorem	
	Exercises	
14	Further Conjugation Results	197
	14.1 Moreau's Decomposition	
	14.2 Proximal Average	
	14.3 Positively Homogeneous Functions	
	14.4 Coercivity	
	14.5 The Conjugate of the Difference	204
	Exercises	
15	Fenchel–Rockafellar Duality	207
	15.1 The Attouch–Brézis Theorem	207
	15.2 Fenchel Duality	211
	15.3 Fenchel–Rockafellar Duality	213
	15.4 A Conjugation Result	217
	15.5 Applications	218
	Exercises	220
16	Subdifferentiability	223
	16.1 Basic Properties	
	16.2 Convex Functions	
	16.3 Lower Semicontinuous Convex Functions	
	16.4 Subdifferential Calculus	233
	Exercises	240

xiv Contents

17	Differentiability of Convex Functions 17.1 Directional Derivatives 17.2 Characterizations of Convexity 17.3 Characterizations of Strict Convexity 17.4 Directional Derivatives and Subgradients 17.5 Gâteaux and Fréchet Differentiability 17.6 Differentiability and Continuity Exercises	241 244 246 247 251 257
18	Further Differentiability Results 18.1 The Ekeland-Lebourg Theorem 18.2 The Subdifferential of a Maximum 18.3 Differentiability of Infimal Convolutions 18.4 Differentiability and Strict Convexity 18.5 Stronger Notions of Differentiability 18.6 Differentiability of the Distance to a Set Exercises	261 264 266 267 268 271
19	Duality in Convex Optimization 19.1 Primal Solutions via Dual Solutions 19.2 Parametric Duality 19.3 Minimization under Equality Constraints 19.4 Minimization under Inequality Constraints Exercises	275 279 283 285
20	Monotone Operators. 20.1 Monotone Operators. 20.2 Maximally Monotone Operators. 20.3 Bivariate Functions and Maximal Monotonicity 20.4 The Fitzpatrick Function Exercises.	293 297 302 304
21	Finer Properties of Monotone Operators 21.1 Minty's Theorem 21.2 The Debrunner–Flor Theorem 21.3 Domain and Range 21.4 Local Boundedness and Surjectivity 21.5 Kenderov's Theorem and Fréchet Differentiability Exercises	311 315 316 318 320
22	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	323 326 327 329

Contents xv

23	Resolvents of Monotone Operators	
	23.1 Definition and Basic Identities	
	23.2 Monotonicity and Firm Nonexpansiveness	
	23.3 Resolvent Calculus	
	23.4 Zeros of Monotone Operators	344
	23.5 Asymptotic Behavior	346
	Exercises	349
24	Sums of Monotone Operators	351
	24.1 Maximal Monotonicity of a Sum	351
	24.2 3* Monotone Operators	354
	24.3 The Brézis–Haraux Theorem	357
	24.4 Parallel Sum	359
	Exercises	361
25	Zeros of Sums of Monotone Operators	363
	25.1 Characterizations	
	25.2 Douglas–Rachford Splitting	
	25.3 Forward–Backward Splitting	
	25.4 Tseng's Splitting Algorithm	
	25.5 Variational Inequalities	375
	Exercises	
26	Fermat's Rule in Convex Optimization	381
	26.1 General Characterizations of Minimizers	381
	26.2 Abstract Constrained Minimization Problems	383
	26.3 Affine Constraints	386
	26.4 Cone Constraints	387
	26.5 Convex Inequality Constraints	389
	26.6 Regularization of Minimization Problems	393
	Exercises	395
27	Proximal Minimization	399
	27.1 The Proximal-Point Algorithm	399
	27.2 Douglas–Rachford Algorithm	
	27.3 Forward–Backward Algorithm	
	27.4 Tseng's Splitting Algorithm	407
	27.5 A Primal–Dual Algorithm	408
	Exercises	
28	Projection Operators	415
	28.1 Basic Properties	415
	28.2 Projections onto Affine Subspaces	417
	28.3 Projections onto Special Polyhedra	419
	28.4 Projections Involving Convex Cones	425
	28.5 Projections onto Epigraphs and Lower Level Sets	

xvi	Contents

	Exercises	429
29	Best Approximation Algorithms229.1 Dykstra's Algorithm229.2 Haugazeau's Algorithm2Exercises2	431 436
Bil	oliographical Pointers	441
Syı	mbols and Notation	443
Re	ferences	449

Chapter 5

Fejér Monotonicity and Fixed Point Iterations

A sequence is Fejér monotone with respect to a set C if each point in the sequence is not strictly farther from any point in C than its predecessor. Such sequences possess very attractive properties that greatly simplify the analysis of their asymptotic behavior. In this chapter, we provide the basic theory for Fejér monotone sequences and apply it to obtain in a systematic fashion convergence results for various classical iterations involving nonexpansive operators.

5.1 Fejér Monotone Sequences

The following notion is central in the study of various iterative methods, in particular in connection with the construction of fixed points of nonexpansive operators.

Definition 5.1 Let C be a nonempty subset of \mathcal{H} and let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} . Then $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C if

$$(\forall x \in C)(\forall n \in \mathbb{N}) \quad ||x_{n+1} - x|| \le ||x_n - x||. \tag{5.1}$$

Example 5.2 Let $(x_n)_{n\in\mathbb{N}}$ be a bounded sequence in \mathbb{R} that is increasing (respectively decreasing). Then $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to $[\sup\{x_n\}_{n\in\mathbb{N}}, +\infty[$ (respectively $]-\infty, \inf\{x_n\}_{n\in\mathbb{N}}]$).

Example 5.3 Let D be a nonempty subset of \mathcal{H} , let $T: D \to D$ be a quasinonexpansive—in particular, nonexpansive—operator such that Fix $T \neq \emptyset$, and let $x_0 \in D$. Set $(\forall n \in \mathbb{N})$ $x_{n+1} = Tx_n$. Then $(x_n)_{n \in \mathbb{N}}$ is Fejér monotone with respect to Fix T.

We start with some basic properties.

Proposition 5.4 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a nonempty subset of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C. Then the following hold:

- (i) $(x_n)_{n\in\mathbb{N}}$ is bounded.
- (ii) For every $x \in C$, $(\|x_n x\|)_{n \in \mathbb{N}}$ converges.
- (iii) $(d_C(x_n))_{n\in\mathbb{N}}$ is decreasing and converges.
- *Proof.* (i): Let $x \in C$. Then (5.1) implies that $(x_n)_{n \in \mathbb{N}}$ lies in $B(x; ||x_0 x||)$.
 - (ii): Clear from (5.1).
- (iii): Taking the infimum in (5.1) over $x \in C$ yields $(\forall n \in \mathbb{N})$ $d_C(x_{n+1}) \leq d_C(x_n)$.

The next result concerns weak convergence.

Theorem 5.5 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a nonempty subset of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C and that every weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$ belongs to C. Then $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in C.

Proof. The result follows from Proposition 5.4(ii) and Lemma 2.39.

Example 5.6 Suppose that \mathcal{H} is infinite-dimensional and let $(x_n)_{n\in\mathbb{N}}$ be an orthonormal sequence in \mathcal{H} . Then $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to $\{0\}$. As seen in Example 2.25, $x_n \to 0$ but $x_n \not\to 0$.

While a Fejér monotone sequence with respect to a closed convex set C may not converge strongly, its "shadow" on C always does.

Proposition 5.7 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a nonempty closed convex subset of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C. Then the shadow sequence $(P_Cx_n)_{n\in\mathbb{N}}$ converges strongly to a point in C.

Proof. It follows from (5.1) and (3.6) that, for every m and n in \mathbb{N} ,

$$||P_{C}x_{n} - P_{C}x_{n+m}||^{2} = ||P_{C}x_{n} - x_{n+m}||^{2} + ||x_{n+m} - P_{C}x_{n+m}||^{2} + 2\langle P_{C}x_{n} - x_{n+m} | x_{n+m} - P_{C}x_{n+m}\rangle \leq ||P_{C}x_{n} - x_{n}||^{2} + d_{C}^{2}(x_{n+m}) + 2\langle P_{C}x_{n} - P_{C}x_{n+m} | x_{n+m} - P_{C}x_{n+m}\rangle + 2\langle P_{C}x_{n+m} - x_{n+m} | x_{n+m} - P_{C}x_{n+m}\rangle \leq d_{C}^{2}(x_{n}) - d_{C}^{2}(x_{n+m}).$$
 (5.2)

Consequently, since $(d_C(x_n))_{n\in\mathbb{N}}$ was seen in Proposition 5.4(iii) to converge, $(P_Cx_n)_{n\in\mathbb{N}}$ is a Cauchy sequence in the complete set C.

Corollary 5.8 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} , let C be a nonempty closed convex subset of \mathcal{H} , and let $x\in C$. Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C and that $x_n \rightharpoonup x$. Then $P_C x_n \to x$.

Proof. By Proposition 5.7, $(P_C x_n)_{n \in \mathbb{N}}$ converges strongly to some point $y \in C$. Hence, since $x - P_C x_n \to x - y$ and $x_n - P_C x_n \to x - y$, it follows from Theorem 3.14 and Lemma 2.41(iii) that $0 \ge \langle x - P_C x_n \mid x_n - P_C x_n \rangle \to \|x - y\|^2$. Thus, x = y.

For sequences that are Fejér monotone with respect to closed affine subspaces, Proposition 5.7 can be strengthened.

Proposition 5.9 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a closed affine subspace of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C. Then the following hold:

- (i) $(\forall n \in \mathbb{N}) P_C x_n = P_C x_0$.
- (ii) Suppose that every weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$ belongs to C. Then $x_n \rightharpoonup P_C x_0$.

Proof. (i): Fix $n \in \mathbb{N}$, $\alpha \in \mathbb{R}$, and set $y_{\alpha} = \alpha P_{C}x_{0} + (1 - \alpha)P_{C}x_{n}$. Since C is an affine subspace, $y_{\alpha} \in C$, and it therefore follows from Corollary 3.20(i) and (5.1) that

$$\alpha^{2} \| P_{C} x_{n} - P_{C} x_{0} \|^{2} = \| P_{C} x_{n} - y_{\alpha} \|^{2}$$

$$\leq \| x_{n} - P_{C} x_{n} \|^{2} + \| P_{C} x_{n} - y_{\alpha} \|^{2}$$

$$= \| x_{n} - y_{\alpha} \|^{2}$$

$$\leq \| x_{0} - y_{\alpha} \|^{2}$$

$$= \| x_{0} - P_{C} x_{0} \|^{2} + \| P_{C} x_{0} - y_{\alpha} \|^{2}$$

$$= d_{C}^{2}(x_{0}) + (1 - \alpha)^{2} \| P_{C} x_{n} - P_{C} x_{0} \|^{2}.$$
(5.3)

Consequently, $(2\alpha - 1)\|P_C x_n - P_C x_0\|^2 \le d_C^2(x_0)$ and, letting $\alpha \to +\infty$, we conclude that $P_C x_n = P_C x_0$.

We now turn our attention to strong convergence properties.

Proposition 5.10 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a subset of \mathcal{H} such that int $C \neq \emptyset$. Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C. Then $(x_n)_{n\in\mathbb{N}}$ converges strongly to a point in \mathcal{H} .

Proof. Take $x \in \text{int } C$ and $\rho \in \mathbb{R}_{++}$ such that $B(x; \rho) \subset C$. Define a sequence $(z_n)_{n \in \mathbb{N}}$ in $B(x; \rho)$ by

$$(\forall n \in \mathbb{N}) \quad z_n = \begin{cases} x, & \text{if } x_{n+1} = x_n; \\ x - \rho \frac{x_{n+1} - x_n}{\|x_{n+1} - x_n\|}, & \text{otherwise.} \end{cases}$$
 (5.4)

Then (5.1) yields $(\forall n \in \mathbb{N}) \|x_{n+1} - z_n\|^2 \le \|x_n - z_n\|^2$ and, after expanding, we obtain

$$(\forall n \in \mathbb{N}) \quad \|x_{n+1} - x\|^2 \le \|x_n - x\|^2 - 2\rho \|x_{n+1} - x_n\|. \tag{5.5}$$

Thus, $\sum_{n\in\mathbb{N}} \|x_{n+1} - x_n\| \le \|x_0 - x\|^2/(2\rho)$ and $(x_n)_{n\in\mathbb{N}}$ is therefore a Cauchy sequence.

Theorem 5.11 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a nonempty closed convex subset of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C. Then the following are equivalent:

- (i) $(x_n)_{n\in\mathbb{N}}$ converges strongly to a point in C.
- (ii) $(x_n)_{n\in\mathbb{N}}$ possesses a strong sequential cluster point in C.
- (iii) $\underline{\lim} d_C(x_n) = 0.$

Proof. (i) \Rightarrow (ii): Clear.

- (ii) \Rightarrow (iii): Suppose that $x_{k_n} \to x \in C$. Then $d_C(x_{k_n}) \leq ||x_{k_n} x|| \to 0$.
- (iii) \Rightarrow (i): Proposition 5.4(iii) implies that $d_C(x_n) \to 0$. Hence, $x_n P_C x_n \to 0$ and (i) follows from Proposition 5.7.

We conclude this section with a linear convergence result.

Theorem 5.12 Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} and let C be a nonempty closed convex subset of \mathcal{H} . Suppose that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to C and that for some $\kappa \in [0,1[$,

$$(\forall n \in \mathbb{N}) \quad d_C(x_{n+1}) \le \kappa d_C(x_n). \tag{5.6}$$

Then $(x_n)_{n\in\mathbb{N}}$ converges linearly to a point $x\in C$; more precisely,

$$(\forall n \in \mathbb{N}) \quad \|x_n - x\| \le 2\kappa^n d_C(x_0). \tag{5.7}$$

Proof. Theorem 5.11 and (5.6) imply that $(x_n)_{n\in\mathbb{N}}$ converges strongly to some point $x\in C$. On the other hand, (5.1) yields

$$(\forall n \in \mathbb{N})(\forall m \in \mathbb{N}) \quad ||x_n - x_{n+m}|| \le ||x_n - P_C x_n|| + ||x_{n+m} - P_C x_n|| \le 2d_C(x_n).$$
 (5.8)

Letting $m \to +\infty$ in (5.8), we conclude that $||x_n - x|| \le 2d_C(x_n)$.

5.2 Krasnosel'skiĭ-Mann Iteration

Given a nonexpansive operator T, the sequence generated by the Banach–Picard iteration $x_{n+1} = Tx_n$ of (1.66) may fail to produce a fixed point of T. A simple illustration of this situation is $T = -\mathrm{Id}$ and $x_0 \neq 0$. In this case, however, it is clear that the *asymptotic regularity* property $x_n - Tx_n \to 0$ does not hold. As we shall now see, this property is critical.

Theorem 5.13 Let D be a nonempty closed convex subset of \mathcal{H} , let $T: D \to D$ be a nonexpansive operator such that $\operatorname{Fix} T \neq \emptyset$, and let $x_0 \in D$. Set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = Tx_n \tag{5.9}$$

and suppose that $x_n - Tx_n \to 0$. Then the following hold:

- (i) $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in Fix T.
- (ii) Suppose that D = -D and that T is odd: $(\forall x \in D) \ T(-x) = -Tx$. Then $(x_n)_{n \in \mathbb{N}}$ converges strongly to a point in Fix T.

Proof. From Example 5.3, $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T.

- (i): Let x be a weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$, say $x_{k_n} \to x$. Since $Tx_{k_n} x_{k_n} \to 0$, Corollary 4.18 asserts that $x \in \text{Fix } T$. Appealing to Theorem 5.5, the assertion is proved.
- (ii): Since D = -D is convex, $0 \in D$ and, since T is odd, $0 \in \operatorname{Fix} T$. Therefore, by Fejér monotonicity, $(\forall n \in \mathbb{N}) \|x_{n+1}\| \leq \|x_n\|$. Thus, there exists $\ell \in \mathbb{R}_+$ such that $\|x_n\| \downarrow \ell$. Now let $m \in \mathbb{N}$. Then, for every $n \in \mathbb{N}$,

$$||x_{n+1+m} + x_{n+1}|| = ||Tx_{n+m} - T(-x_n)|| \le ||x_{n+m} + x_n||,$$
 (5.10)

and, by the parallelogram identity.

$$||x_{n+m} + x_n||^2 = 2(||x_{n+m}||^2 + ||x_m||^2) - ||x_{n+m} - x_n||^2.$$
 (5.11)

However, since $Tx_n - x_n \to 0$, we have $\lim_n \|x_{n+m} - x_n\| = 0$. Therefore, since $\|x_n\| \downarrow \ell$, (5.10) and (5.11) yield $\|x_{n+m} + x_n\| \downarrow 2\ell$ as $n \to +\infty$. In turn, we derive from (5.11) that $\|x_{n+m} - x_n\|^2 \le 2(\|x_{n+m}\|^2 + \|x_m\|^2) - 4\ell^2 \to 0$ as $m, n \to +\infty$. Thus, $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence and $x_n \to x$ for some $x \in D$. Since $x_{n+1} \to x$ and $x_{n+1} = Tx_n \to Tx$, we have $x \in \text{Fix } T$.

We now turn our attention to an alternative iterative method, known as the *Krasnosel'skiĭ–Mann algorithm*.

Theorem 5.14 (Krasnosel'skiĭ–Mann algorithm) Let D be a nonempty closed convex subset of \mathcal{H} , let $T: D \to D$ be a nonexpansive operator such that Fix $T \neq \emptyset$, let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in [0,1] such that $\sum_{n \in \mathbb{N}} \lambda_n (1 - \lambda_n) = +\infty$, and let $x_0 \in D$. Set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n + \lambda_n (Tx_n - x_n). \tag{5.12}$$

Then the following hold:

- (i) $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T.
- (ii) $(Tx_n x_n)_{n \in \mathbb{N}}$ converges strongly to 0.
- (iii) $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in Fix T.

Proof. Since $x_0 \in D$ and D is convex, (5.12) produces a well-defined sequence in D.

(i): It follows from Corollary 2.14 and the nonexpansiveness of T that, for every $y \in \text{Fix } T$ and $n \in \mathbb{N}$,

$$||x_{n+1} - y||^2 = ||(1 - \lambda_n)(x_n - y) + \lambda_n (Tx_n - y)||^2$$

$$= (1 - \lambda_n)||x_n - y||^2 + \lambda_n ||Tx_n - Ty||^2$$

$$- \lambda_n (1 - \lambda_n)||Tx_n - x_n||^2$$

$$\leq ||x_n - y||^2 - \lambda_n (1 - \lambda_n)||Tx_n - x_n||^2.$$
 (5.13)

Hence, $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T.

(ii): We derive from (5.13) that $\sum_{n\in\mathbb{N}} \lambda_n (1-\lambda_n) \|Tx_n - x_n\|^2 \le \|x_0 - y\|^2$. Since $\sum_{n\in\mathbb{N}} \lambda_n (1-\lambda_n) = +\infty$, we have $\underline{\lim} \|Tx_n - x_n\| = 0$. However, for every $n\in\mathbb{N}$,

$$||Tx_{n+1} - x_{n+1}|| = ||Tx_{n+1} - Tx_n + (1 - \lambda_n)(Tx_n - x_n)||$$

$$\leq ||x_{n+1} - x_n|| + (1 - \lambda_n)||Tx_n - x_n||$$

$$= ||Tx_n - x_n||.$$
(5.14)

Consequently, $(\|Tx_n - x_n\|)_{n \in \mathbb{N}}$ converges and we must have $Tx_n - x_n \to 0$.

(iii): Let x be a weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$, say $x_{k_n} \to x$. Then it follows from Corollary 4.18 that $x \in \operatorname{Fix} T$. In view of Theorem 5.5, the proof is complete.

Proposition 5.15 Let $\alpha \in]0,1[$, let $T \colon \mathcal{H} \to \mathcal{H}$ be an α -averaged operator such that $\operatorname{Fix} T \neq \emptyset$, let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in $[0,1/\alpha]$ such that $\sum_{n \in \mathbb{N}} \lambda_n (1-\alpha\lambda_n) = +\infty$, and let $x_0 \in \mathcal{H}$. Set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n + \lambda_n (Tx_n - x_n). \tag{5.15}$$

Then the following hold:

- (i) $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T.
- (ii) $(Tx_n x_n)_{n \in \mathbb{N}}$ converges strongly to 0.
- (iii) $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in Fix T.

Proof. Set $R = (1 - 1/\alpha)\operatorname{Id} + (1/\alpha)T$ and $(\forall n \in \mathbb{N})$ $\mu_n = \alpha \lambda_n$. Then Fix $R = \operatorname{Fix} T$ and R is nonexpansive by Proposition 4.25. In addition, we rewrite (5.15) as $(\forall n \in \mathbb{N})$ $x_{n+1} = x_n + \mu_n(Rx_n - x_n)$. Since $(\mu_n)_{n \in \mathbb{N}}$ lies in [0, 1] and $\sum_{n \in \mathbb{N}} \mu_n(1 - \mu_n) = +\infty$, the results follow from Theorem 5.14.

Corollary 5.16 Let $T: \mathcal{H} \to \mathcal{H}$ be a firmly nonexpansive operator such that $\operatorname{Fix} T \neq \emptyset$, let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in [0,2] such that $\sum_{n \in \mathbb{N}} \lambda_n (2 - \lambda_n) = +\infty$, and let $x_0 \in \mathcal{H}$. Set $(\forall n \in \mathbb{N})$ $x_{n+1} = x_n + \lambda_n (Tx_n - x_n)$. Then the following hold:

- (i) $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T.
- (ii) $(Tx_n x_n)_{n \in \mathbb{N}}$ converges strongly to 0.

(iii) $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in Fix T.

Proof. In view of Remark 4.24(iii), apply Proposition 5.15 with $\alpha = 1/2$.

Example 5.17 Let $T: \mathcal{H} \to \mathcal{H}$ be a firmly nonexpansive operator such that Fix $T \neq \emptyset$, let $x_0 \in \mathcal{H}$, and set $(\forall n \in \mathbb{N})$ $x_{n+1} = Tx_n$. Then $(x_n)_{n \in \mathbb{N}}$ converges weakly to a point in Fix T.

The following type of iterative method involves a mix of compositions and convex combinations of nonexpansive operators.

Corollary 5.18 Let $(T_i)_{i\in I}$ be a finite family of nonexpansive operators from \mathcal{H} to \mathcal{H} such that $\bigcap_{i\in I} \operatorname{Fix} T_i \neq \emptyset$, and let $(\alpha_i)_{i\in I}$ be real numbers in]0,1[such that, for every $i\in I$, T_i is α_i -averaged. Let p be a strictly positive integer, for every $k\in\{1,\ldots,p\}$, let m_k be a strictly positive real number, and suppose that i: $\{(k,l)\mid k\in\{1,\ldots,p\}, l\in\{1,\ldots,m_k\}\}\to I$ is surjective and that $\sum_{k=1}^p \omega_k = 1$. For every $k\in\{1,\ldots,p\}$, set $I_k=\{\mathrm{i}(k,1),\ldots,\mathrm{i}(k,m_k)\}$, and set

$$\alpha = \max_{1 \le k \le p} \rho_k, \quad \text{where} \quad (\forall k \in \{1, \dots, p\}) \quad \rho_k = \frac{m_k}{m_k - 1 + \frac{1}{\max_{i \in L} \alpha_i}}, \quad (5.16)$$

and let $(\lambda_n)_{n\in\mathbb{N}}$ be a sequence in $[0,1/\alpha]$ such that $\sum_{n\in\mathbb{N}} \lambda_n (1-\alpha\lambda_n) = +\infty$. Furthermore, let $x_0 \in \mathcal{H}$ and set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n + \lambda_n \left(\sum_{k=1}^p \omega_k T_{i(k,1)} \cdots T_{i(k,m_k)} x_n - x_n \right). \tag{5.17}$$

Then $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in $\bigcap_{i\in I} \operatorname{Fix} T_i$.

Proof. Set $T = \sum_{k=1}^{p} \omega_k R_k$, where $(\forall k \in \{1, \dots, p\})$ $R_k = T_{\mathrm{i}(k,1)} \cdots T_{\mathrm{i}(k,m_k)}$. Then (5.17) reduces to (5.15) and, in view of Proposition 5.15, it suffices to show that T is α -averaged and that $\mathrm{Fix}\,T = \bigcap_{i \in I} \mathrm{Fix}\,T_i$. For every $k \in \{1, \dots, p\}$, it follows from Proposition 4.32 and (5.16) that R_k is ρ_k -averaged and, from Corollary 4.37 that $\mathrm{Fix}\,R_k = \bigcap_{i \in I_k} \mathrm{Fix}\,T_i$. In turn, we derive from Proposition 4.30 and (5.16) that T is α -averaged and, from Proposition 4.34, that $\mathrm{Fix}\,T = \bigcap_{k=1}^{p} \mathrm{Fix}\,R_k = \bigcap_{k=1}^{p} \bigcap_{k \in I_k} \mathrm{Fix}\,T_i = \bigcap_{i \in I} \mathrm{Fix}\,T_i$.

Remark 5.19 It follows from Remark 4.24(iii) that Corollary 5.18 is applicable to firmly nonexpansive operators and, a fortiori, to projection operators by Proposition 4.8.

Corollary 5.18 provides an algorithm to solve a *convex feasibility problem*, i.e., to find a point in the intersection of a family of closed convex sets. Here are two more examples.

Example 5.20 (string-averaged relaxed projections) Let $(C_i)_{i \in I}$ be a finite family of closed convex sets such that $C = \bigcap_{i \in I} C_i \neq \varnothing$. For every $i \in I$, let $\beta_i \in]0,2[$ and set $T_i = (1-\beta_i)\mathrm{Id} + \beta_i P_{C_i}$. Let p be a strictly positive integer; for every $k \in \{1,\ldots,p\}$, let m_k be a strictly positive integer and ω_k be a strictly positive real number, and suppose that i: $\{(k,l) \mid k \in \{1,\ldots,p\}, l \in \{1,\ldots,m_k\}\} \to I$ is surjective and that $\sum_{k=1}^p \omega_k = 1$. Furthermore, let $x_0 \in \mathcal{H}$ and set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = \sum_{k=1}^{p} \omega_k T_{i(k,1)} \cdots T_{i(k,m_k)} x_n.$$
 (5.18)

Then $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in C.

Proof. For every $i \in I$, set $\alpha_i = \beta_i/2 \in]0,1[$. Since, for every $i \in I$, Proposition 4.8 asserts that P_{C_i} is firmly nonexpansive, Corollary 4.29 implies that T_i is α_i -averaged. Borrowing notation from Corollary 5.18, we note that for every $k \in \{1,\ldots,p\}$, $\max_{i \in I_k} \alpha_i \in]0,1[$, which implies that $\rho_k \in]0,1[$ and thus that $\alpha \in]0,1[$. Altogether, the result follows from Corollary 5.18 with $\lambda_n \equiv 1$.

Example 5.21 (parallel projection algorithm) Let $(C_i)_{i\in I}$ be a finite family of closed convex subsets of \mathcal{H} such that $C = \bigcap_{i\in I} C_i \neq \emptyset$, let $(\lambda_n)_{n\in\mathbb{N}}$ be a sequence in [0,2] such that $\sum_{n\in\mathbb{N}} \lambda_n(2-\lambda_n) = +\infty$, let $(\omega_i)_{i\in I}$ be strictly positive real numbers such that $\sum_{i\in I} \omega_i = 1$, and let $x_0 \in \mathcal{H}$. Set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n + \lambda_n \left(\sum_{i \in I} \omega_i P_i x_n - x_n \right), \tag{5.19}$$

where, for every $i \in I$, P_i denotes the projector onto C_i . Then $(x_n)_{n \in \mathbb{N}}$ converges weakly to a point in C.

Proof. This is an application of Corollary 5.16(iii) with $T = \sum_{i \in I} \omega_i P_i$. Indeed, since the operators $(P_i)_{i \in I}$ are firmly nonexpansive by Proposition 4.8, their convex combination T is also firmly nonexpansive by Example 4.31. Moreover, Proposition 4.34 asserts that $\operatorname{Fix} T = \bigcap_{i \in I} \operatorname{Fix} P_i = \bigcap_{i \in I} C_i = C$. Alternatively, apply Corollary 5.18.

5.3 Iterating Compositions of Averaged Operators

Our first result concerns the asymptotic behavior of iterates of a composition of averaged nonexpansive operators with possibly no common fixed point.

Theorem 5.22 Let D be a nonempty weakly sequentially closed (e.g., closed and convex) subset of \mathcal{H} , let m be a strictly positive integer, set I =

 $\{1,\ldots,m\}$, let $(T_i)_{i\in I}$ be a family of nonexpansive operators from D to D such that $\mathrm{Fix}(T_1\cdots T_m)\neq\varnothing$, and let $(\alpha_i)_{i\in I}$ be real numbers in]0,1[such that, for every $i\in I$, T_i is α_i -averaged. Let $x_0\in D$ and set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = T_1 \cdots T_m x_n. \tag{5.20}$$

Then $x_n - T_1 \cdots T_m x_n \to 0$, and there exist points $y_1 \in \text{Fix } T_1 \cdots T_m$, $y_2 \in \text{Fix } T_2 \cdots T_m T_1, \ldots, y_m \in \text{Fix } T_m T_1 \cdots T_{m-1}$ such that

$$x_n \rightharpoonup y_1 = T_1 y_2, \tag{5.21}$$

$$T_m x_n \rightharpoonup y_m = T_m y_1, \tag{5.22}$$

$$T_{m-1}T_mx_n \rightharpoonup y_{m-1} = T_{m-1}y_m,$$
 (5.23)

:

$$T_3 \cdots T_m x_n \rightharpoonup y_3 = T_3 y_4, \tag{5.24}$$

$$T_2 \cdots T_m x_n \rightharpoonup y_2 = T_2 y_3. \tag{5.25}$$

Proof. Set $T = T_1 \cdots T_m$ and $(\forall i \in I)$ $\beta_i = (1 - \alpha_i)/\alpha_i$. Now take $y \in \text{Fix } T$. The equivalence (i) \Leftrightarrow (iii) in Proposition 4.25 yields

$$||x_{n+1} - y||^{2} = ||Tx_{n} - Ty||^{2}$$

$$\leq ||T_{2} \cdots T_{m} x_{n} - T_{2} \cdots T_{m} y||^{2}$$

$$- \beta_{1} ||(\operatorname{Id} - T_{1}) T_{2} \cdots T_{m} x_{n} - (\operatorname{Id} - T_{1}) T_{2} \cdots T_{m} y||^{2}$$

$$\leq ||x_{n} - y||^{2} - \beta_{m} ||(\operatorname{Id} - T_{m}) x_{n} - (\operatorname{Id} - T_{m}) y||^{2}$$

$$- \beta_{m-1} ||(\operatorname{Id} - T_{m-1}) T_{m} x_{n} - (\operatorname{Id} - T_{m-1}) T_{m} y||^{2} - \cdots$$

$$- \beta_{2} ||(\operatorname{Id} - T_{2}) T_{3} \cdots T_{m} x_{n} - (\operatorname{Id} - T_{2}) T_{3} \cdots T_{m} y||^{2}$$

$$- \beta_{1} ||(\operatorname{Id} - T_{1}) T_{2} \cdots T_{m} x_{n} - (T_{2} \cdots T_{m} y - y)||^{2}.$$
 (5.26)

Therefore, $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to Fix T and

$$(\mathrm{Id} - T_m)x_n - (\mathrm{Id} - T_m)y \to 0,$$
 (5.27)

$$(\mathrm{Id} - T_{m-1})T_m x_n - (\mathrm{Id} - T_{m-1})T_m y \to 0,$$
 (5.28)

:

$$(\mathrm{Id} - T_2)T_3 \cdots T_m x_n - (\mathrm{Id} - T_2)T_3 \cdots T_m y \to 0,$$
 (5.29)

$$(\mathrm{Id} - T_1)T_2 \cdots T_m x_n - (T_2 \cdots T_m y - y) \to 0.$$
 (5.30)

Upon adding (5.27)–(5.30), we obtain $x_n - Tx_n \to 0$. Hence, since T is nonexpansive as a composition of nonexpansive operators, it follows from Theorem 5.13(i) that $(x_n)_{n\in\mathbb{N}}$ converges weakly to some point $y_1 \in \operatorname{Fix} T$, which provides (5.21). On the other hand, (5.27) yields $T_m x_n - x_n \to T_m y_1 - y_1$. So altogether $T_m x_n \to T_m y_1 = y_m$, and we obtain (5.22). In turn, since (5.28) asserts that $T_{m-1}T_m x_n - T_m x_n \to T_{m-1}y_m - y_m$, we ob-

tain $T_{m-1}T_mx_n
ightharpoonup T_{m-1}y_m = y_{m-1}$, hence (5.23). Continuing this process, we arrive at (5.25).

As noted in Remark 5.19, results on averaged nonexpansive operators apply in particular to firmly nonexpansive operators and projectors onto convex sets. Thus, by specializing Theorem 5.22 to convex projectors, we obtain the iterative method described in the next corollary, which is known as the POCS (Projections Onto Convex Sets) algorithm in the signal recovery literature.

Corollary 5.23 (POCS algorithm) Let m be a strictly positive integer, set $I = \{1, ..., m\}$, let $(C_i)_{i \in I}$ be a family of nonempty closed convex subsets of \mathcal{H} , let $(P_i)_{i \in I}$ denote their respective projectors, and let $x_0 \in \mathcal{H}$. Suppose that $\text{Fix}(P_1 \cdots P_m) \neq \emptyset$ and set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = P_1 \cdots P_m x_n. \tag{5.31}$$

Then there exists $(y_1, \ldots, y_m) \in C_1 \times \cdots \times C_m$ such that $x_n \rightharpoonup y_1 = P_1 y_2$, $P_m x_n \rightharpoonup y_m = P_m y_1$, $P_{m-1} P_m x_n \rightharpoonup y_{m-1} = P_{m-1} y_m$, ..., $P_3 \cdots P_m x_n \rightharpoonup y_3 = P_3 y_4$, and $P_2 \cdots P_m x_n \rightharpoonup y_2 = P_2 y_3$.

Proof. This follows from Proposition 4.8 and Theorem 5.22. \Box

Remark 5.24 In Corollary 5.23, suppose that, for some $j \in I$, C_j is bounded. Then $\operatorname{Fix}(P_1 \cdots P_m) \neq \emptyset$. Indeed, consider the circular composition of the m projectors given by $T = P_j \cdots P_m P_1 \cdots P_{j-1}$. Then Proposition 4.8 asserts that T is a nonexpansive operator that maps the nonempty bounded closed convex set C_j to itself. Hence, it follows from Theorem 4.19 that there exists a point $x \in C_j$ such that Tx = x.

The next corollary describes a periodic projection method to solve a convex feasibility problem.

Corollary 5.25 Let m be a strictly positive integer, set $I = \{1, ..., m\}$, let $(C_i)_{i \in I}$ be a family of closed convex subsets of \mathcal{H} such that $C = \bigcap_{i \in I} C_i \neq \emptyset$, let $(P_i)_{i \in I}$ denote their respective projectors, and let $x_0 \in \mathcal{H}$. Set $(\forall n \in \mathbb{N})$ $x_{n+1} = P_1 \cdots P_m x_n$. Then $(x_n)_{n \in \mathbb{N}}$ converges weakly to a point in C.

Proof. Using Corollary 5.23, Proposition 4.8, and Corollary 4.37, we obtain $x_n \rightharpoonup y_1 \in \text{Fix}(P_1 \cdots P_m) = \bigcap_{i \in I} \text{Fix} P_i = C$. Alternatively, this is a special case of Example 5.20.

Remark 5.26 If, in Corollary 5.25, all the sets are closed affine subspaces, so is C and we derive from Proposition 5.9(i) that $x_n \to P_C x_0$. Corollary 5.28 is classical, and it states that the convergence is actually strong in this case. In striking contrast, the example constructed in [146] provides a closed hyperplane and a closed convex cone in $\ell^2(\mathbb{N})$ for which alternating projections converge weakly but not strongly.

Exercises 85

The next result will help us obtain a sharper form of Corollary 5.25 for closed affine subspaces.

Proposition 5.27 Let $T \in \mathcal{B}(\mathcal{H})$ be nonexpansive and let $x_0 \in \mathcal{H}$. Set $V = \operatorname{Fix} T$ and $(\forall n \in \mathbb{N})$ $x_{n+1} = Tx_n$. Then $x_n \to P_V x_0 \Leftrightarrow x_n - x_{n+1} \to 0$.

Proof. If $x_n \to P_V x_0$, then $x_n - x_{n+1} \to P_V x_0 - P_V x_0 = 0$. Conversely, suppose that $x_n - x_{n+1} \to 0$. We derive from Theorem 5.13(ii) that there exists $v \in V$ such that $x_n \to v$. In turn, Proposition 5.9(i) yields $v = P_V x_0$.

Corollary 5.28 (von Neumann–Halperin) Let m be a strictly positive integer, set $I = \{1, ..., m\}$, let $(C_i)_{i \in I}$ be a family of closed affine subspaces of \mathcal{H} such that $C = \bigcap_{i \in I} C_i \neq \emptyset$, let $(P_i)_{i \in I}$ denote their respective projectors, let $x_0 \in \mathcal{H}$, and set

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = P_1 \cdots P_m x_n. \tag{5.32}$$

Then $x_n \to P_C x_0$.

Proof. Set $T = P_1 \cdots P_m$. Then T is nonexpansive, and Fix T = C by Corollary 4.37.

We first assume that each set C_i is a linear subspace. Then T is odd, and Theorem 5.22 implies that $x_n - Tx_n \to 0$. Thus, by Proposition 5.27, $x_n \to P_C x_0$.

We now turn our attention to the general affine case. Since $C \neq \emptyset$, there exists $y \in C$ such that for every $i \in I$, $C_i = y + V_i$, i.e., V_i is the closed linear subspace parallel to C_i , and C = y + V, where $V = \bigcap_{i \in I} V_i$. Proposition 3.17 implies that, for every $x \in \mathcal{H}$, $P_C x = P_{y+V} x = y + P_V (x - y)$ and $(\forall i \in I)$ $P_i x = P_{y+V} x = y + P_{V_i} (x - y)$. Using these identities repeatedly, we obtain

$$(\forall n \in \mathbb{N}) \quad x_{n+1} - y = (P_{V_1} \cdots P_{V_m})(x_n - y). \tag{5.33}$$

Invoking the already verified linear case, we get $x_n - y \to P_V(x_0 - y)$ and conclude that $x_n \to y + P_V(x_0 - y) = P_C x_0$.

Exercises

Exercise 5.1 Find a nonexpansive operator $T: \mathcal{H} \to \mathcal{H}$ that is not firmly nonexpansive and such that, for every $x_0 \in \mathcal{H}$, the sequence $(T^n x_0)_{n \in \mathbb{N}}$ converges weakly but not strongly to a fixed point of T.

Exercise 5.2 Construct a non-Cauchy sequence $(x_n)_{n\in\mathbb{N}}$ in \mathbb{R} that is asymptotically regular, i.e., $x_n - x_{n+1} \to 0$.

Exercise 5.3 Find an alternative proof of Theorem 5.5 based on Corollary 5.8 in the case when C is closed and convex.

Exercise 5.4 Let C be a nonempty subset of \mathcal{H} and let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathcal{H} that is Fejér monotone with respect to C. Show that $(x_n)_{n\in\mathbb{N}}$ is Fejér monotone with respect to $\overline{\operatorname{conv}} C$.

Exercise 5.5 Let $T: \mathcal{H} \to \mathcal{H}$ be a nonexpansive operator such that Fix $T \neq \emptyset$, and let $(x_n)_{n \in \mathbb{N}}$ be a sequence in \mathcal{H} such that

- (i) for every $x \in \text{Fix } T$, $(\|x_n x\|)_{n \in \mathbb{N}}$ converges;
- (ii) $x_n Tx_n \to 0$.

Show that $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in Fix T.

Exercise 5.6 Find a nonexpansive operator $T: \mathcal{H} \to \mathcal{H}$ that is not firmly nonexpansive and such that, for every $x_0 \in \mathcal{H}$, the sequence $(T^n x_0)_{n \in \mathbb{N}}$ converges weakly but not strongly to a fixed point of T.

Exercise 5.7 Let m be a strictly positive integer, set $I = \{1, ..., m\}$, let $(C_i)_{i \in I}$ be a family of closed convex subsets of \mathcal{H} such that $C = \bigcap_{i \in I} C_i \neq \emptyset$, and let $(P_i)_{i \in I}$ be their respective projectors. Derive parts (ii) and (iii) from (i) and Theorem 5.5, and also from Corollary 5.18.

- (i) Let $i \in I$, let $x \in C_i$, and let $y \in \mathcal{H}$. Show that $||P_i y x||^2 \le ||y x||^2 ||P_i y y||^2$.
- (ii) Set $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N})$$
 $x_{n+1} = \frac{1}{m} (P_1 x_n + P_1 P_2 x_n + \dots + P_1 \dots P_m x_n).$ (5.34)

- (a) Let $x \in C$ and $n \in \mathbb{N}$. Show that $||x_{n+1} x||^2 \le ||x_n x||^2 (1/m) \sum_{i \in I} ||P_i x_n x||^2$.
- (b) Let x be a weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$. Show that $x\in C$.
- (c) Show that $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in C.
- (iii) Set $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = \frac{1}{m-1} (P_1 P_2 x_n + P_2 P_3 x_n + \dots + P_{m-1} P_m x_n). \tag{5.35}$$

- (a) Let $x \in C$ and $n \in \mathbb{N}$. Show that $||x_{n+1} x||^2 \le ||x_n x||^2 \sum_{i=1}^{m-1} (||P_{i+1}x_n x_n||^2 + ||P_iP_{i+1}x_n P_{i+1}x_n||^2)/(m-1)$.
- (b) Let x be a weak sequential cluster point of $(x_n)_{n\in\mathbb{N}}$. Show that $x\in C$.
- (c) Show that $(x_n)_{n\in\mathbb{N}}$ converges weakly to a point in C.

Index

 3^* monotone, 354-356base of neighborhoods, 23 best approximation, 44, 278, 410 accretive operator, 293 best approximation algorithm, acute cone, 105 410, 411, 431 addition of functions, 6 biconjugate function, 181, 185, addition of set-valued operators, 2 190, 192 adjoint of a linear operator, 31 biconjugation theorem, 190 affine constraint, 386 bilinear form, 39, 384, 385 affine hull, 1, 93 Bishop-Phelps theorem, 107 affine minorant, 133, 134, 168, 184, Boltzmann-Shannon entropy, 137, 191, 192, 207, 223, 224 139 affine operator, 3, 35, 44, 418 boundary of a set, 7 affine projector, 48, 62 bounded below, 134, 184 affine subspace, 1, 43, 108 Brézis-Haraux theorem, 358 almost surely, 29 Bregman distance, 258 alternating minimizations, 162 Browder-Göhde-Kirk theorem, 64 alternating projection method, Brøndsted-Rockafellar theorem. 406, 432 236 Anderson–Duffin theorem, 361 Bunt-Motzkin theorem, 318 angle bounded operator, 361, 362 Burg's entropy, 138, 151, 244 Apollonius's identity, 30, 46 approximating curve, 64 Cantor's theorem, 17 Cauchy sequence, 17, 24, 34, 46 asymptotic center, 117, 159, 195 asymptotic regularity, 78 Cauchy–Schwarz inequality, 29 at most single-valued, 2 Cayley transform, 349 Attouch-Brézis condition, chain, 3 210. chain rule, 40 216 characterization of minimizers, Attouch–Brézis theorem, 207, 209 381 autoconjugate function, 190, 239, Chebyshev center, 249, 250 303 averaged nonexpansive operator, Chebyshev problem, 47 67, 72, 80–82, 294, 298, 440 Chebyshev set, 44–47, 318 closed ball, 16 Baillon-Haddad theorem, 270 closed convex hull, 43 ball, 43 closed range, 220 Banach-Alaoglu theorem, 34 closed set, 7, 8 Banach-Picard theorem, 20 closure of a set, 7, 22 Banach-Steinhaus theorem, 31 cluster point, 7, 8 barrier cone, 103, 156

base of a topology, 7, 9, 16, 33

cocoercive operator, 60, 61, 68, 70, cyclically monotone operator, 326 270, 294, 298, 325, 336, 339. Debrunner-Flor theorem, 315 355, 370, 372, 377, 379, 438 decreasing function, 5 coercive function, 158–161, 165, decreasing sequence of convex sets, 202-204, 210 48, 417 cohypomonotone operator, 337 demiclosedness principle, 63 common fixed points, 71 dense hyperplane, 123 compact set, 7, 8, 13 dense set, 7, 33, 123, 232 complementarity problem, 376 descent direction, 248, 249 complementary slackness, 291, 422 descent lemma, 270 complete metric space, 17 diameter of a set, 16 composition of set-valued operadirected set, 3, 4, 22, 27 tors, 2 directional derivative, 241, 247 concave function, 113 discontinuous linear functional, cone, 1, 87, 285, 287, 376, 387, 389, 32, 123, 169 425 discrete entropy, 140 conical hull, 87 distance, 27 conjugate function, 181 distance to a set, 16, 20, 24, 32, 34, conjugation, 181, 197, 226, 230 44, 49, 98, 167, 170, 173, 177, constrained minimization prob-183, 185, 188, 238, 271, 272 lem, 283, 285, 383 domain of a function, 5, 6, 113 continuity, 9 domain of a set-valued operator, 2 continuous affine minorant, 168 domain of continuity, 11 continuous convex function, 123, Douglas-Rachford algorithm, 366, 136 376, 401, 404 continuous function, 11 dual cone, 96 continuous linear functional, 31 dual optimal value, 214 continuous operator, 9, 63 dual problem, 212, 214, 275, 279, convergence of a net, 7 408 convex combination, 44 dual solution, 275, 279 convex cone, 87, 89, 179, 183, 285, duality, 211, 213, 275 duality gap, 212, 214-216, 221 convex feasibility problem, 81, 84 Dykstra's algorithm, 431, 432 convex function, 113, 155 convex hull, 43, 44 Eberlein-Smulian theorem, 35 convex integrand, 118, 138, 193, effective domain of a function, 6 238 Ekeland variational principle, 19 convex on a set, 114, 125 Ekeland-Lebourg theorem, 263 convex programming problem, 290 enlargement of a monotone operaconvex set, 43 tor, 309 convexity with respect to a cone, entropy of a random variable, 139 285 epi-sum, 167 core, 90, 95, 123, 207, 210, 214, epigraph, 5, 6, 12, 15, 113, 119, 216, 241, 271 133, 168 counting measure, 140 equality constraint, 283

Fréchet gradient, 38 Euclidean space, 28 Fréchet topological space, 23 even function, 186 eventually in a set, 4 frequently in a set, 4 evolution equation, 313 function, 5 exact infimal convolution, G_{δ} set, 19, 263, 320 170, 171, 207, 209, 210 Gâteaux derivative, 37 exact infimal postcomposition, 178 Gâteaux differentiability, 37–39, exact modulus of convexity, 144-243, 244, 246, 251, 252, 254, 146 257, 267 existence of minimizers, 157, 159 gauge, 120, 124, 202 expected value, 29 generalized inverse, 50, 251, 360, extended real line, 4 361, 395, 418 extension, 297 generalized sequence, 4 F_{σ} set, 24 global minimizer, 223 Farkas's lemma, 99, 106 gradient, 38, 176, 243, 244, 266, farthest-point operator, 249, 296 267, 382 Fejér monotone, 75, 83, 86, 160, gradient operator, 38 400 graph, 5 Fenchel conjugate, 181 graph of a set-valued operator, 2 Fenchel duality, 211 Hölder continuous gradient, 269 Fenchel-Moreau theorem, 190 half-space, 32, 33, 43, 419, 420 Fenchel–Rockafellar duality, 213, Hamel basis, 32 275, 282, 408 hard thresholder, 61 Fenchel-Young inequality, 185, Haugazeau's algorithm, 436, 439 226 Hausdorff distance, 25 Fermat's rule, 223, 235, 381 Hausdorff space, 7, 16, 33 firmly nonexpansive operator, 59, hemicontinous operator, 298, 325 61-63, 68, 69, 73, 80, 81, 176, Hessian, 38, 243, 245, 246 270, 294, 298, 335, 337, 436 Hilbert direct sum, 28, 226 first countable space, 23 Hilbert space, 27 Fitzpatrick function, 304, 311, 351 Huber's function, 124 Fitzpatrick function of order n, hyperplane, 32, 34, 48, 123 330 fixed point, 62, 79–81 increasing function, 5 fixed point iterations, 75 fixed point set, 20, 62–64, 436 forward-backward algorithm, 370,

377, 405, 438, 439

Fréchet derivative, 38, 39, 257

rithm, 375

320

forward-backward-forward algo-

Fréchet differentiability, 38, 176,

177, 243, 253, 254, 268–270,

increasing function, 5 increasing sequence of convex sets, 416 indicator function, 12, 113, 173, 227 inequality constraint, 285, 389 infimal convolution, 167, 187, 207, 210, 237, 266, 359 infimal postcomposition, 178, 187, 199, 218, 237 infimum, 5, 157, 159, 184, 188

infimum of a function, 6 Lipschitz continuous, 20, 31, 59, infinite sum, 27 123, 176, 229, 339 initial condition, 295 Lipschitz continuous gradient, integral function, 118, 138, 193, 269-271, 405-407, 439 238 local minimizer, 156 interior of a set, 7, 22, 90, 123 locally bounded operator, 316, inverse of a monotone operator, 319, 344 locally Lipschitz continuous, 20, 295 inverse of a set-valued operator, 2, 122 lower bound, 3 inverse strongly monotone operalower level set, 5, 6, 148, 427 tor, 60 lower semicontinuity, 10, 129 lower semicontinuous, 10, 12 Jensen's inequality, 135 lower semicontinuous convex envelope, 130, 185, 192, 193, 207 Karush-Kuhn-Tucker conditions, lower semicontinuous convex func-393 tion, 122, 129, 132, 185 Kenderov theorem, 320 lower semicontinuous envelope, 14, kernel of a linear operator, 32 23 Kirszbraun-Valentine theorem, lower semicontinuous function. 337 Krasnosel'skiĭ-Mann algorithm, lower semicontinuous infimal con-78, 79 volution, 170, 210 Lagrange multiplier, 284, 287, 291, marginal function, 13, 120, 152 386-388, 391 max formula, 248 Lagrangian, 280, 282 maximal element, 3 Lax-Milgram theorem, 385 maximal monotone operator, 297 least element, 3 maximal monotonicity and contileast-squares solution, 50 nuity, 298 Lebesgue measure, 29 maximal monotonicity of a sum, Legendre function, 273 Legendre transform, 181 maximally cyclically monotone op-Legendre–Fenchel transform, 181 erator, 326 level set, 5, 6, 12, 15, 132, 158, 203, maximally monotone extension, 383 316, 337 limit inferior, 5 maximally monotone operator, limit superior, 5 297, 298, 311, 335, 336, 338, line segment, 1, 43, 54, 132 339, 438 linear convergence, 20, 78, 372, maximum of a function, 6 377, 406, 407 measure space, 28, 295 linear equations, 50 metric space, 16 linear functional, 32 metric topology, 16, 33, 34 linear monotone operator, 296– metrizable topology, 16, 23, 34

midpoint convex function, 141

298, 355

midpoint convex set, 57 obtuse cone, 105 minimax, 218 odd operator, 79, 379 minimization in a product space, open ball, 16 403 open set, 7 minimization problem, 13, 156, operator splitting algorithm, 366 381, 393, 401, 402, 404-406 Opial's condition, 41 minimizer, 156, 157, 159, 163, 243, optimal value, 214 order, 3 384 minimizing sequence, 6, 13, 160, orthogonal complement, 27 399 orthonormal basis, 27, 37, 161, minimum of a function, 6, 243 301, 313, 344 Minkowski gauge, 120, 124, 202 orthonormal sequence, 34 Minty's parametrization, 340 outer normal, 32 Minty's theorem, 311 parallel linear subspace, 1 modulus of convexity, 144 parallel projection algorithm, 82 monotone extension, 297 parallel splitting algorithm, 369, monotone linear operator, 296 404 monotone operator, 244, 293, 311, parallel sum of monotone opera-351, 363 tors, 359 monotone set, 293 parallelogram identity, 29 Moore-Penrose inverse, 50 parametric duality, 279 Moreau envelope, 173, 175, 176, paramonotone operator, 323, 385 183, 185, 187, 197, 198, 270, partial derivative, 259 271, 276, 277, 334, 339, 342 partially ordered set, 3 Moreau's conical decomposition, Pasch-Hausdorff envelope, 172, 98 179 Moreau's decomposition, 198 periodicity condition, 295 Moreau–Rockafellar theorem, 204 perspective function, 119, 184 POCS algorithm, 84 negative orthant, 5 negative real number, 4 pointed cone, 88, 105 neighborhood, 7 pointwise bounded operator famnet, 4, 5, 22, 27, 53, 314 ily, 31 polar cone, 96, 110 nonexpansive operator, 59, 60, 62, 63, 79, 159, 270, 294, 298, polar set, 110, 202, 206, 428 336, 348, 439 polarization identity, 29 nonlinear equation, 325 polyhedral cone, 388, 389 norm, 27, 35, 40, 115, 118, 144, polyhedral function, 216–218, 381, 147, 150, 151, 183, 199, 231, 383, 388, 389 252 polyhedral set, 216, 383 polyhedron, 419 norm topology, 33 normal cone, 101, 227, 230, 238, positive operator, 60 272, 304, 334, 354, 383, 389 positive orthant, 5, 426 normal equation, 50 positive real number, 4 positive semidefinite matrix, 426 normal vector, 107

positively homogeneous function, proximal-point algorithm, 345. 143, 201, 229, 278 399, 438 positively homogeneous operator, proximinal set, 44–46 3 proximity operator, 175, 198, 199, 233, 243, 244, 271, 334, 339. power set, 2 primal optimal value, 214 342-344, 375, 381, 382, 401, primal problem, 212, 214, 275, 279, 402, 404, 405, 415, 428 408 pseudocontractive operator, 294 primal solution, 275, 279 pseudononexpansive operator, 294 primal-dual algorithm, 408 quadratic function, 251 probability simplex, 426 quasiconvex function, 148, 157, probability space, 29, 139 160, 165 product topology, 7 quasinonexpansive operator, 59, projection algorithm, 431, 439 62, 71, 75 projection onto a ball, 47 quasirelative interior, 91 projection onto a convex cone, 97, 98, 425 random variable, 29, 135, 139, 194 projection onto a half-space, 419 range of a set-valued operator, 2 projection onto a hyperplane, 48, range of a sum of operators, 357, 358 projection onto a hyperslab, 419 recession cone, 103 projection onto a linear subspace, recession function, 152 recovery of primal solutions, 275, projection onto a lower level set, 408 427 reflected resolvent, 336, 363, 366 projection onto a polar set, 428 regularization, 393 projection onto a ray, 426 regularized minimization problem, projection onto a set, 44 projection onto an affine subspace, relative interior, 90, 96, 123, 210, 48, 77, 417 216, 234 projection onto an epigraph, 133, resolvent, 333, 335, 336, 366, 370, 427 373 projection operator, 44, 61, 62, reversal of a function, 186, 236, 175, 177, 334, 360, 361, 415 projection theorem, 46, 238 reversal of an operator, 3, 340 projection-gradient algorithm, 406 Riesz-Fréchet representation, 31 projector, 44, 61 right-shift operator, 330, 356 proper function, 6, 132 Rådström's cancellation, 58 proximal average, 199, 205, 271, 307 saddle point, 280–282 proximal mapping, 175 scalar product, 27 proximal minimization, 399 second Fréchet derivative, 38 proximal-gradient algorithm, 405, second Gâteaux derivative, 38 439 second-order derivative, 245, 246

selection of a set-valued operator, strictly quasiconvex function, 149, self-conjugacy, 183, 185 strictly quasinonexpansive operaself-dual cone, 96, 186 tor, 59, 71 self-polar cone, 186 string-averaged relaxed projecseparable Hilbert space, 27, 194 tions, 82 separated sets, 55 strong convergence, 33, 37 separation, 55 strong relative interior, 90, 95, 96, sequential cluster point, 7, 15, 33 209, 210, 212, 215, 217, 234, sequential topological space, 16, 23 236, 381 sequentially closed, 15, 16, 53, 231, strong separation, 55 300, 301 strong topology, 33 sequentially compact, 15, 16, 36 strongly convex function, 144, 159, sequentially continuous, 15, 16 188, 197, 270, 276, 324, 406 sequentially lower semicontinuous, strongly monotone operator, 323, 325, 336, 344, 372 15, 129 set-valued operator, 2 subadditive function, 143 subdifferentiable function, shadow sequence, 76 223,sigma-finite measure space, 194 247 Slater condition, 391 subdifferential, 223, 294, 304, 312, slope, 168 324, 326, 354, 359, 381, 383 soft thresholder, 61, 199 subdifferential of a maximum, 264 solid cone, 88, 105 subgradient, 223 sublinear function, 143, 153, 156, span of a set, 1 splitting algorithm, 375, 401, 402, 241 404, 405 subnet, 4, 8, 22 sum of linear subspaces, 33 Stampacchia's theorem, 384, 395 standard unit vectors, 28, 89, 92 sum of monotone operators, 351 steepest descent direction, 249 sum rule for subdifferentials, 234 strict contraction, 64 summable family, 27 strict epigraph, 180 supercoercive function, 158, 159, strictly convex function, 114, 144, 172, 203, 210, 229 161, 267, 324 support function, 109, 156, 183, strictly convex on a set, 114 195, 201, 229, 240 strictly convex set, 157 support point, 107, 109, 164 strictly decreasing function, 5 supporting hyperplane, 107, 109 strictly increasing function, 5 supremum, 5, 129, 188 supremum of a function, 6 strictly monotone operator, 323, 344 surjective monotone operator, 318, strictly negative real number, 4 320, 325, 358 strictly nonexpansive operator, tangent cone, 100 325 time-derivative operator, 295, 312, strictly positive operator, 246 strictly positive orthant, 5 Toland–Singer duality, 205 strictly positive real number, 4

topological space, 7 topology, 7 totally ordered set, 3 trace of a matrix, 28 translation of an operator, 3 Tseng's splitting algorithm, 373, 378, 407 Tykhonov regularization, 393

unbounded net, 314
uniform boundedness principle, 31
uniformly convex function, 144,
147, 324, 394, 399
uniformly convex on a set, 144,
147, 324, 407
uniformly convex set, 164, 165

uniformly convex set, 164, 165 uniformly monotone on a set, 324 uniformly monotone on bounded sets, 346, 367, 373, 376, 378, 408

uniformly monotone operator, 323, 325, 344, 354, 358, 367, 373, 376, 378, 408

uniformly quasiconvex function, 149, 163

upper bound, 3 upper semicontinuous function, 11, 124, 281

value function, 279, 289 variational inequality, 375–378, 383

Volterra integration operator, 308 von Neumann's minimax theorem, 218

von Neumann–Halperin theorem, 85

weak closure, 53 weak convergence, 33, 36, 79–81 weak sequential closure, 53 weak topology, 33 weakly closed, 33–35, 45, 53 weakly compact, 33–35 weakly continuous operator, 33, 35, 62, 418 weakly lower semicontinuous, 35, 129

weakly lower semicontinuous function, 33

weakly open, 33

weakly sequentially closed, 33–35, 53

weakly sequentially compact, 33, 35

weakly sequentially continuous operator, 343, 426

weakly sequentially lower semicontinuous, 129

Weierstrass theorem, 13

Yosida approximation, 333, 334, 336, 339, 345, 347, 348

zero of a monotone operator, 344, 345, 347, 381, 438 zero of a set-valued operator, 2

zero of a set-valued operator, 2 zero of a sum of operators, 363, 366, 369, 375